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Topical Categories of Domains

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It is shown how many techniques of categorical domain theory can be expressed in the general context of topical categories (where \topical" means internal in the category Top of Grothendieck toposes with geometric morphisms). The underlying topos machinery is hidden by using a geometric form of constructive mathematics, which enables toposes as "generalized topological spaces" to be treated in a transparently spatial way, and also shows the constructivity of the arguments. The theory of strongly algebraic (SFP) domains is given as a case study in which the topical category is Cartesian closed.

1. Introduction

1.1. "Topology-free spaces"

"Always topologize!"(Stone 1938)

"A topos is a generalized topological space."(Grothendieck 1972)

Taken together, these two dicta imply a general mathematical programme of topologization in which classes are replaced by toposes: instead of the class of widgets we consider the topos classifying widgets (i.e. the topos whose points are widgets). The topos not only determines the class of widgets, but simultaneously, and inseparably, embodies the generalized topological structure on the generalized space of widgets.

This resort to toposes may seem at first sight an unacceptably burdensome technical overhead, but in fact the practical mathematical consequences can be surprisingly unobtrusive. Toposes classify theories in the so-called \geometric" logic, and it is quite in order to treat a topos as a "space" whose points are the models of the theory and to treat a geometric morphism (a generalized continuous map between generalized topological spaces) as a transformation of points of one such space into points of another. As long as the transformation is defined uniformly and in accordance with a geometrically constructive discipline it will yield a geometric morphism, and so we see continuity under a new light as uniformity combined with geometricity. Our Stone-Grothendieck generalized topologization is thus achieved by working with a geometric "Stone-Grothendieck" mathematics". Since this often has the effect of avoiding explicit discussion of topological structure (lattices of opens or categories of sheaves), we shall refer to this view of toposes as one of "topology-free spaces" $-$ which is not to say that these generalized spaces do not

have any topology, but rather that it is intrinsic and hidden. Introductory accounts of the ideas are in Vickers (1996, 1998a); more technical justication is in Vickers (1997a).

To explain how this works, we first have to be very clear about the dual nature of toposes: as Mac Lane and Moerdijk (1992) say right at the outset, a topos can be considered both as a "generalized topological space" and as a "generalized universe of sets". But the formal definitions say that the topos is the generalized universe of sets, and in these terms it is extremely difficult to sustain the generalized space view. Hence although this view is a fundamental one of which experienced topos theorists are fully aware, it tends to get obscured in the exposition.

We shall explicitly separate the two viewpoints by reserving the word *topos* for the generalized spaces. (This runs counter to the general usage, but has etymological support in that it treats toposes as the objects of which *topology* is the study.) The generalized universes of sets – specifically, those categories (otherwise known as Grothendieck toposes) that satisfy the conditions of Giraud's theorem (see Johnstone (1977)) – will be called geometric universes or GUs (in Vickers (1993a, 1995a, 1995b) they are called Giraud frames or G-frames). The distinction is analogous to that between locales and frames (in Johnstone (1982); or, in Joyal and Tierney (1984), the distinction between spaces and locales), and indeed we hope that the techniques of spatial reasoning for locales that are investigated in Vickers (1995) can be developed for toposes too. Similarly, a GU homomorphism will be a functor that preserves finite limits and arbitrary colimits $-$ hence, the inverse image part of a geometric morphism. For a topos D , the corresponding geometric universe will be written SD.

The present paper is in large measure a case study for this topologization programme in which it is applied to domain theory, and one deliberate aim is to give a topos-theoretic account that looks as much as possible just like constructive domain theory. A preliminary account in the form of lecture slides has already appeared (Vickers 1992a).

Let us now lay down the ground rules for this geometric mathematics (technical justification is in Vickers $(1997a)$.

- (1) "Geometric" mathematics comprises those constructions and properties that can be interpreted in any geometric universe and are preserved by GU homomorphisms.
- (2) If certain structures are described as being the models of a geometric theory T , that is to say, they are specied by structure and properties within geometric mathematics, then there is a corresponding "classifying" topos $[T]$ of which those structures are the points.

Recall the usual notion of a *geometric theory presentation* $-$ a many-sorted, infinitary, first-order theory presentation, in which the axioms take the form $\phi \vdash_{\mathbf{x}} \psi$. Here x is a finite list of sorted variables and ϕ and ψ are *geometric* formulae (the only connectives allowed are arbitrary disjunction, finitary conjunction, sorted equality and existential quantication) whose free variables are all taken from x. (Details can be found in Makkai and Reyes (1977); also in Johnstone (1977) and Mac Lane and Moerdijk (1992), though for simplicity they treat the *coherent* theories, restricted to the finitary logic.) We shall be more liberal and admit presentations that use geometric constructions as type constructors, to create new types out of the given sorts (the base types). Function and predicate symbols will be allowed to use the derived types in their arities.

- (3) If such a theory in (2) is "essentially propositional", that is to say, it has no sorts (other than what can be constructed geometrically out of thin air), then the corresponding topos is actually a locale. We have no need to distinguish between locales and localic toposes, since our notation explicitly distinguishes between frames D and geometric universes SD .
- (4) Suppose D and E are two toposes. Then construction of points of E out of points of D, if it is geometric, describes a geometric morphism (or map) from D to E.
- (5) Geometric morphisms between locales are the same as continuous maps.

Consequently, we describe a locale or a topos by giving a geometric description of its points; and we describe a continuous map or a geometric morphism by giving a geometric description of how it transforms points to points. No discussion of topology is then needed because the geometricity already covers that, and so locales and toposes appear as "topology-free spaces". Of course, this phrase is introduced in direct contrast with the common description of locales as \point-free topologies". The point-free topology is the frame of opens, treated as an algebraic structure in its own right. The "topology-free space" methods are to work rather with presentations by generators and relations, and then in a switch of emphasis to treat them not as algebraic presentations of the frames but as geometric descriptions of the points.

We shall examine what is allowed in this geometric mathematics, but first let us mention some things that are not allowed.

- $\overline{\hspace{1cm}}$ The logic is non-classical. Intuitionistic logic is valid in geometric universes, but in general excluded middle and choice are not valid. More subtly, intuitionistic negation is not preserved by GU homomorphisms, and nor are implication and universal quantification $-$ so we can't use them in general, though we shall on occasion use the intuitionistic formulae in proving geometric results. The geometric logic is therefore more restricted than intuitionistic logic. However, if we can prove or postulate that two propositions P and Q are logical complements $(P \wedge Q \vdash false, true \vdash P \vee Q),$ then that fact is preserved by GU homomorphisms and so gives an instance of a geometric negation.
- We can't use exponentials X^Y , powersets $\mathcal{P}X$, or the subobject classifier Ω none of these is preserved by GU homomorphisms.

I shall not attempt to formalize the geometric constructions, but they include finite limits, set-indexed colimits, image factorization, monicness, epiness, inclusion between subobjects, finite intersections and arbitrary set-indexed unions of subobjects, existential quantification, free algebra constructions, $\mathbb N$ (natural numbers), $\mathbb Q$ (rationals), Kuratowski finiteness, finite powersets (free semilattices) $\mathcal{F}X$, universal quantification bounded over finite objects.

A couple of specific issues worth mentioning are decidability and finiteness. Equality is part of the geometric logic, but inequality is not (because there is no negation). Nonetheless, certain "decidable" sets come equipped with inequality, a relation complementary to equality – two good examples are N and Q. Finiteness is – as remarked above – K_{u} -

ratowski finiteness (Johnstone 1977): X is Kuratowski finite iff the free semilattice $\mathcal{F}X$ on X has an element T such that $\{x\} \subset T$ for every x in X. This notion can sometimes behave surprisingly. For instance, subsets of finite sets, or intersections of finite subsets, need not themselves be finite. Section 2.1 provides a technical discussion.

$Notes -$

- 1 If T is a geometric theory, then the corresponding geometric universe $S[T]$ is exactly the category that is usually referred to as the classifying topos of T . The notation can be read either as Sheaves over the topos $[T]$, or as Sets with an adjoined generic model of T .
- 2 When we refer to the points of $[T]$, the models of T, these models might be in an arbitrary geometric universe SD . D is known as the *stage of definition* of the point, and the theory of classifying toposes shows that points of $[T]$ at stage D are the same as maps from D to [T]. Models in the initial GU $S = S1$ of sets, i.e. maps from 1 to $[T]$, are known as *global* points.
- 3 If f and g are two maps from [T] to [T], then a natural transformation from f to g is a geometric construction, given a model M of T, of a homomorphism from $f(M)$ to $g(M)$.
- 4 Toposes, maps and natural transformations are the 0-, 1- and 2-cells of a 2-category Top. We shall look at it more closely later, but let us note immediately that the \min -categories $\textbf{top}(T | T | T)$ (which is equivalent to the category of models of T) in $S[T]$ are not arbitrary categories – they have all filtered colimits (Johnstone 1977).

1.2. Topologizing domain theory

It has long been recognized that domains are topological spaces under their Scott topology. Normally, they are also sober (at least for continuous dcpos, though not, by Johnstone (1981), for arbitrary ones) and hence can be equivalently treated as locales. This provides a technical basis for treating domains as, fundamentally, topological structures (specically, for us, locales) rather than ordered structures (e.g. dcpos). Since any locale has both an order (specialization) on points and all directed joins of points, we can find a least fixpoint for any endomap of any locale with bottom point (a *local* locale), thus giving us the essential domain theoretic machinery used to interpret recursion. Moreover, there is a conceptual basis for the primacy of topology in that the order is often understood as an "information" order, and the topology provides a direct account of that information $-$ each open represents a finitely observable amount of it, as argued, for instance, in Vickers (1989) or Abramsky (1991).

Therefore, as an application of Stone's dictum, we shall take it as axiomatic that a domain is fundamentally a locale rather than a partially ordered set of any kind. This can sometimes seem a retrograde step. For instance, unlike the category of dcpos, the category of locales is not Cartesian closed – though this advantage for general dcpos is lost in the algebraic case and only recovered in strongly algebraic domains after substantial work. Nonetheless, the results of the paper will show that the topologization programme holds together and in fact gives a greater unity to the techniques of domain theory.

By the remarks of Section 1.1, domains as locales are also toposes. It turns out that

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domain theoretic constructions such as products, coproducts and exponentials are special cases of the more general topos constructions, and we shall prove this. In particular, the existence of least fixpoints for continuous endomaps of domains with bottom turns out to be a special case of the existence of initial fixpoints for arbitrary endomaps of local toposes (toposes with initial points) $-$ in effect, local toposes are algebraically complete in the appropriately transferred sense of Freyd (1991).

However, the methods go considerably beyond this. Nice enough domains can be presented by information systems of various flavours (e.g. Larsen and Winskel 1984; Vickers 1993; or indeed the slightly different methods of Abramsky 1991) that are the models of geometric theories, and moreover the continuous maps between the domains are equivalent to "approximable mappings" between information systems, which are also the models of geometric theories. Fixing a flavour of information system, we therefore get two toposes [IS] and [AM]. (AM is the theory of two information systems and an approximable mapping between them.) We also have maps src and tar : $[AM] \rightarrow [IS]$ giving the source and target, a map id : $[IS] \rightarrow [AM]$ giving the identity approximable mappings, and more that in short make an internal category in $\text{Top}-a$ topical category. (The fact that Top is a 2-category greatly complicates the idea of internal category in it, and a definitive account of such things (Hyland and Moerdijk unpublished) hasn't appeared yet. However, the topical categories we study will all in a certain sense represent full subcategories of Top, in that the approximable mappings correspond to arbitrary maps (as geometric morphisms) between the corresponding domains (as toposes), and this gives us a somewhat more solid base on which to rest the internal category structure.) We find that the topical category has, internally, much of the structure of the corresponding category of domains, and in particular for strongly algebraic domains the topical category is internally Cartesian closed. This is a stronger result than appears at first sight, for with some other well-known CCCs such as **Set**, the Cartesian closedness is not internal in the corresponding topical category: essentially this is because exponentiation of sets is not geometric.

The topos setting now begins to pay off more decisively. In particular, we can use the result mentioned above on algebraic completeness of local toposes to find not only fixpoints within domains, but also fixpoints among domains, i.e. solutions of domain equations. This is most easily seen for domains with bottom, when [IS] is local (the singleton information system $\{\perp\}$ is initial) and any map $F : [IS] \to [IS]$, i.e. any uniform, geometric construction of information systems from information systems, has an initial algebra: this will solve the domain equation $D = F(D)$. The key point is that toposes automatically have all the filtered colimits that abstract categorical domain theory has to postulate, and the uniform, geometric definitions of geometric morphisms suffice to give us the required continuity, preservation of these filtered colimits.

Note that F is necessarily functorial, but that is with respect to the homomorphisms between information systems -2 -cells in Top - and not the approximable mappings. In the strongly algebraic case, which is internally Cartesian closed, we have a map $F(X) = [X \Rightarrow X]$ that is not functorial with respect to continuous maps. However, the homomorphisms turn out to correspond to adjunctions between the domains so that we painlessly discover the well-known technical trick from domain theory that regains

functoriality. (Actually, domain theory normally uses embedding-projection pairs, not general adjunctions. The difference corresponds to the constructivist issue of whether the information system order is decidable or not.)

1.3. Overview of the paper

Following this introduction, we move in Section 2 to the technical background. Much of this is already known, though perhaps some of the detailed proofs have not been set out before. However, I do not know of convenient references and certainly not in the "generalized space" language that I am using.

In section 3 we look at some examples of topical categories, and in particular at two ways of constructing them. An "intrinsic" topical category captures the idea, given any topos D , of a category whose objects are points of D and whose morphisms are homomorphisms. These are simple, but inadequate for our domain theory. We need the slightly more complicated notion of "display" topical category. This starts from an exponentiable map $p : E \to D$, and captures the idea of a category whose objects are points of D, but whose morphisms are maps between pullbacks of p. It is relatively rare for these topical categories to be Cartesian closed, and we illustrate this with some counterexamples.

Section 4 treats the particular case of strongly algebraic domains, in which the topical category is Cartesian closed, in some detail. Its domain-theoretic substance is largely taken from Abramsky (1991). Its purpose is not so much to present the results in a new way, different from Abramsky's $-$ the apparent differences are often ones of expositional taste rather than anything $else - but to show how unobtrusive the new, topos-theoretic$ foundations are.

Section 5 addresses domain equations and their solution.

Section 6 discusses what is achieved by the topical methods, and speculates on revised foundations using Joyal's Arithmetic Universes.

2. Technical background

This section gathers together diverse technical results under four headings:

- 2.1 Finite power sets
- 2.2 The 2-category **Top** of toposes
- $2.3 -$ Lifting in Top
- $2.4 -$ Algebraic dcpos

2.1. Finite power sets

The geometric account of finiteness (by which we mean Kuratowski finiteness (Kock et al. 1975; Johnstone 1977)) has some unexpected behaviour, a notorious example being that subsets of finite sets need not themselves be finite (Kock et al. 1975). Nonetheless, it fits well with observational intuitions that a set is finite iff you can give a finite list of all its elements. (But note that if equality is not decidable then you can't necessarily eliminate duplicates from the list.) Two finite sets are equal iff every element of each is

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also an element of the other. To understand the paradox of subsets, suppose S is finite and $T = \{s \in S \mid \phi(s)\}\.$ To list all the elements of T, we also need negative information $\neg \phi(s)$ in order to know which elements of S can be omitted from the list.

We recap here some basic properties and constructions relating to finite sets, and in particular the fact that bounded universal quantification over a finite set is geometric (Johnstone and Linton 1978). Much of this seems to be well-known folklore, but I don't know of any convenient reference for the ideas and shall summarize them here.

The first step is to construct the finite power set $\mathcal{F}X$ over X, and this is done as the free (join) semilattice. As it happens, by a theorem of Mikkelson this can be constructed in any elementary topos as the U-subsemilattice of $\mathcal{P}X$ generated by the singletons (see Theorem 9.16 in Johnstone 1977). However, in the context of geometric universes it is perhaps more convenient to see the construction as a special case of the existence of free algebras for any single-sorted algebraic theory that is finitary enough (Theorem 6.43 in Johnstone 1977). Moreover, by Lemma 6.44 there, the free algebra construction is preserved by GU homomorphisms: in other words, free algebra constructions are "geometric".

 $\mathcal{F}X$ is the set of Kuratowski finite subsets of X. From now on we shall omit "Kuratowski": when we say $finite$, we mean Kuratowski finite.

We have already noted that subsets of finite sets need not be finite; here are some other unexpected behaviours.

- $\overline{}$ Finite unions of finite sets are undoubtedly finite (just concatenate the lists of elements), but finite intersections are not. For a start, the empty intersection of finite subsets of X is the whole of X , which certainly need not be finite. More subtly, if S and T are finite then $S \cap T$ need not be because to discover what are all the elements of $S \cap T$ you must be able to determine the negative information of when $x \notin S$ (or T).
- $-$ The cardinality of a finite set is not defined in general. To know that you have counted exactly how many elements there are in $\{w, x, y, z\}$, you need to know all the equalities and inequalities amongst the elements, and the negative information is not always available geometrically.

(Often the problem is one of decidability, i.e. lack of negative information. For instance, if ϕ is decidable and S is finite then $\{u \in S \mid \phi(u)\}\$ is finite; and if X has decidable equality, a binary predicate \neq that's a complement of $=$, then $\mathcal{F}X$ has binary intersections and there is a cardinality function from $\mathcal{F}X$ to \mathbb{N} .)

Definition 2.1.1. (Finitely bounded universal quantification) Let $\phi(x, y)$ be a predicate on X - Y . Then the predicate 8x ² S:(x; y) on FX - Y is dened as

$$
\bigvee_{n \in \mathbb{N}} \exists x_1, \ldots, x_n. (S = \{x_1, \ldots, x_n\} \wedge \bigwedge_{i=1}^n \phi(x_i, y))
$$

An alternative and perhaps more precise definition would make direct use of the free semilattice property of $\mathcal{F}X$: if $f: X \to \mathcal{P}Y$ corresponds to $\phi(x, y)$ (i.e. $\phi(x, y)$ holds iff $y \in f(x)$, then this extends to a unique semilattice homomorphism from $\mathcal{F}X$ to $\mathcal{P}Y$ under \cap , and this corresponds to $\forall x \in S.\phi(x, y)$. However, the definition given makes

explicit that this is a geometric construction on ϕ . To show that it really is bounded universal quantication, one shows the characterizing proof-theoretic adjunction:

, proposition 2.1.2. Let $\{y_i\}$ and $\{y_j\}$ are predicated on X - and X - 2.2. Then

 $\psi(y) \vdash_{S,y} \forall x \in S. \phi(x, y)$ iff $\phi(y) \land x \in S \vdash_{S,y,x} \phi(x, y)$

Next, we give some basic inductive and recursive tools for dealing with finite sets.

Theorem 2.1.3. (Simple F-induction) Let $\phi(S)$ be a predicate on $\mathcal{F}X$ such that $\phi(\emptyset)$ (base case), and if $\phi(S)$ then $\phi({x} \cup S)$ for all $x : X$ (induction step). Then $\phi(S)$ holds for all S.

Proof. Let M be the subset of $\mathcal{F}X$ comprising those elements S for which $\forall T$: $\mathcal{F}X.(\phi(T) \to \phi(S \cup T))$. M is a subsemilattice, and by the induction step it contains the singletons, so it is the whole of $\mathcal{F}X$. From $S \in M$, and the base case $\phi(\emptyset)$, we deduce $\phi(S)$.

Note that although the statement of this Theorem is geometric, the proof is not $-$ it uses intuitionistic formulae. We conjecture that there is a geometric proof. \blacksquare

(In Theorem 2.1.11 we shall prove a stronger induction principle.)

 \mathcal{L} . The contract is zero in the contract in the contra

 $1 \quad \forall x, x, y, f(x, f(x, y)) = f(x, f(x, y))$ 2 $\forall x, y. f(x, f(x, y)) = f(x, y)$

the there is a unique g : FX - T . T . T . T . That is a unit

$$
\forall y. g(\emptyset, y) = y
$$

$$
\forall x, y. g(\{x\}, y) = f(x, y)
$$

$$
\forall S, T, y. g(S \cup T, y) = g(S, g(T, y))
$$

Proof. Let $f: A \to Y$ be the curried form of f, Let M_0 be the image of f in Y , which is a monoid under composition, and let M be the submonoid generated by M_0 . Conditions 1 and 2 say that the elements of M_0 are commuting idempotents. Because they commute, M is commutative, for consider the centralizer of M_0 in $Y = \text{the set of }$ elements that commute with everything in M_0 . This is a submonoid containing M_0 , and hence containing all of M , and so everything in M commutes with everything in M_0 . Therefore the centralizer of M contains M_0 and hence all of M, so M is commutative. Now we can show that the set of idempotent elements of M is a submonoid containing all of M_0 , and hence is the whole of M , so M is a semilattice. It follows that f factors uniquely via a semilattice homomorphism $g: \mathcal{F} \Lambda \to M$, which uncurries to the required g .

Theorem 2.1.5. Let f : X - Y ! Y satisfy conditions 1 and 2 of Lemma 2.1.4, and let $y_0: Y$. Then there is a unique $h: \mathcal{F}X \to Y$ satisfying

$$
h(\emptyset) = y_0
$$

$$
\forall x, S. h(\lbrace x \rbrace \cup S) = f(x, h(S))
$$

Proof. Let g be the function obtained in Lemma 2.1.4, and define $h(S) = g(S, y_0)$.

Then $h(\emptyset) = g(\emptyset, y_0) = y_0$, and $h(\lbrace x \rbrace \cup S) = g(\lbrace x \rbrace \cup S, y_0) = g(\lbrace x \rbrace, g(S, y_0)) =$ $f(x, h(S))$. Uniqueness follows by *F*-induction.

Using F -induction, we can easily prove a number of results.

Theorem 2.1.6.

1 $\forall x \in S$: $(\phi(x) \vee \psi(x)) \vdash_{S: \mathcal{F}X}$

$$
\exists S_{\phi}, S_{\psi}.(S = S_{\phi} \cup S_{\psi} \land \forall x \in S_{\phi}. \phi(x) \land \forall x \in S_{\psi}. \psi(x))
$$

- 2 Decidable subsets of finite sets are finite (Kock et al. 1975): if S is finite and $\phi(x)$ is decidable, then $\{x \in S \mid \phi(x)\}\$ is finite. (Use 1 with ψ the complement of ϕ .)
- 3 (Johnstone 1984) $\forall x \in S.(\phi(x) \vee \psi(x)) \vdash_{S:FX} \forall x \in S.\phi(x) \vee \exists x \in S.\psi(x)$ Note that the analogous deduction with S infinite is intuitionistically unsound, so this result is saying something about finite boundedness. It is directly analogous to the relation " $\Box(\phi \lor \psi) \vdash \Box \phi \lor \Diamond \psi$ " seen in the Vietoris powerlocale.
- 4 If ϕ is decidable, with complement ψ , then $\forall x \in S$. $\phi(x)$ and $\exists x \in S$. $\psi(x)$ are complements.
- 5 If X has decidable equality, then on $\mathcal{F}X$ we have that \in is decidable $(x_0 \notin S)$ is equivalent to $\forall x \in S$. $x \neq x_0$, that the intersection of two finite sets is still finite (use 2 with $S \cap T = \{x \in S \mid x \in T\}$; see Acuña-Ortega and Linton (1979)) and that each finite set has a cardinality.
- ⁶ 8x ² S:9y : Y :(x; y) `S:FX 9U : F(X Y):(fst(U) = S ^ U)
- 7 Emptiness is a decidable property in $\mathcal{F}X$: the formula $S = \emptyset$ has complement $\exists x$: $X.x \in S$.

(We write $\mathcal{F}_1 X$ for the set of non-empty finite subsets of X.)

Proof. The induction arguments are easy. For 7, we see by induction that $\vdash_{S:\mathcal{F}X} S =$ μ ; μ - μ , μ , μ is a set that μ is μ is that μ is μ is the following interest in Fig. (made into a partial order – indeed, a lattice – by \perp < T. The function from X to I, mapping every element to \top , extends to a semilattice homomorphism $f : \mathcal{F}X \to (I,\vee)$. If $S = \emptyset$ then $f(S) = \bot$, while if $x \in S$ then $f(S) = f({x} \cup S) = \top \vee f(S) = \top$, so we cannot have both.

We shall now use $\mathcal{F}\text{-induction}$ and recursion to prove a sequence of finiteness results: that if S and T are set T , then so are S \sim . The set T are S and the set T relations from S to T . The framework of the proof is the same in each case, and can be . The second with S - α - α - α - α , - α function from α , α function from α as a function from α \mathbf{r} . The first function is not too different is not to different function \mathbf{r}_i , the contribution is not free semilattice property and so on), but more important to us is its specification, that S - T = f(x; y) : x ² S ^ y ² T ^g { in other words,

$$
(x,y) \in S \times T \dashv \vdash_{x:X,y:Y,S: \mathcal{F}X,T: \mathcal{F}Y} x \in S \land y \in T
$$

To show that the recursive definition works correctly, i.e. that it satisfies its specification, one can use $\mathcal{F}\text{-induction}$ in a routine sort of way, but in practice this amounts to an assumption that the recursive calls work correctly and we shall make this assumption without comment. (Compare this with the method of recursion variants as set out in Morgan (1990) or Broda et al. (1994).)

 \mathbf{P} . The so is \mathbf{P} and T are the so is S \mathbf{P} and T are \mathbf{P} are so is S \mathbf{P} . Then so is S \mathbf{P}

Proof. Let X, Y be any types. We dene - : FX - FY ! F(X - Y) such that

$$
(x, y) \in S \times T \dashv\vdash_{x:X,y:Y,S: \mathcal{F}X,T: \mathcal{F}Y} x \in S \wedge y \in T
$$

If b : Y , then there is a unique function from FX to F(X - Y), written S 7! S - fbg, such that f , f is and f and f is that f is

$$
(x, y) \in \emptyset \times \{b\} \Leftrightarrow \textbf{false} \Leftrightarrow x \in \emptyset \land y = b
$$

$$
(x, y) \in (\{a\} \cup S) \times \{b\} \Leftrightarrow (x, y) \in \{(a, b)\} \vee (x, y) \in S \times \{b\}
$$

$$
\Leftrightarrow (x = a \land y = b) \vee (x \in S \land y = b) \text{ (induction)}
$$

$$
\Leftrightarrow x \in \{a\} \cup S \land y = b
$$

 N : FX, we can define the unique function T \sim such that S \sim such that S \sim such that S \sim and S - (fb \mathbb{F}_i) such that it satisfies its species in the proof that it satisfies its species in the proof similar.

Corollary 2.1.8.

- ¹ `S:FX;T1;T2 :FY ^S (T1 [T2) ⁼ ^S T1 [^S T2
- ² `S1;S2:FX;T :FY (S1 [S2) ^T ⁼ S1 ^T [S2 T

Proof. These could be proved inductively from the construction in Proposition 2.1.7, but much simpler is to use the specification. For instance, for 1,

$$
(x, y) \in S \times (T_1 \cup T_2) \Leftrightarrow x \in S \land y \in (T_1 \cup T_2)
$$

\n
$$
\Leftrightarrow x \in S \land (y \in T_1 \lor y \in T_2)
$$

\n
$$
\Leftrightarrow (x \in S \land y \in T_1) \lor (x \in S \land y \in T_2)
$$

\n
$$
\Leftrightarrow (x, y) \in S \times T_1 \cup S \times T_2
$$

2 is completely similar, despite the asymmetry of the underlying construction. \blacksquare

Proposition 2.1.9. (Kock et al. 1975) If S is finite, then so is $\mathcal{F}S$. (By Theorem 2.1.6 (7) and (2), it follows that \mathcal{F}_1S is too.)

Proof. If X is any type, we desire a function $\mathcal{F}: \mathcal{F}X \to \mathcal{F}\mathcal{F}X$ such that $T \in$ $\mathcal{F}(S) \dashv_{S,T:\mathcal{F}X} T \subseteq S$. Let F be the unique function such that

$$
\mathcal{F}(\emptyset) = \{\emptyset\}
$$

$$
\mathcal{F}(\{a\} \cup S) = \mathcal{F}(S) \cup \{\{a\} \cup T | T \in \mathcal{F}(S)\}\
$$

 $({G \}_q \cup T | T \in \mathcal{F}(S)$ is the direct image of $\mathcal{F}(S)$ under the function from $\mathcal{F}X$ to itself that maps T to ${a \cup T}$.) Of course, we must check the conditions for F-recursion. In other words, if $U : \mathcal{FF}X$, then we want

$$
(\mathcal{U} \cup \{\{a\} \cup T | T \in \mathcal{U}\}) \cup \{\{b\} \cup U | U \in \mathcal{U} \cup \{\{a\} \cup T | T \in \mathcal{U}\}\}\
$$

= ... same thing with *a* and *b* interchanged

which is clear because the expression reduces to

$$
\mathcal{U} \cup \{\{a\} \cup T | T \in \mathcal{U}\} \cup \{\{b\} \cup U | U \in \mathcal{U}\} \cup \{\{a\} \cup \{b\} \cup T | T \in \mathcal{U}\}\
$$

Also, we want that when $a = b$ the expression reduces to $\mathcal{U} \cup \{\{a\} \cup T | T \in \mathcal{U}\}\)$, which again is clear.

Now we must show that the definition satisfies the specification. $T \in \mathcal{F}(\emptyset) \Leftrightarrow T = \emptyset \Leftrightarrow$ $T \subset \emptyset$, and it remains to show the case for $\{a\} \cup S$.

$$
\begin{aligned} T \in \mathcal{F}(\{a\} \cup S) & \Leftrightarrow T \in \mathcal{F}(S) \vee \exists U \in \mathcal{F}(S).T = \{a\} \cup U \\ & \Leftrightarrow T \subseteq S \vee \exists U: \mathcal{FF}X. (U \subseteq S \wedge T = \{a\} \cup U) \end{aligned}
$$

(Note the assumption, justified as an F-induction hypothesis, that $T \in \mathcal{F}(S) \Leftrightarrow T \subseteq$ S.) Certainly this implies that $T \subseteq \{a\} \cup S$. For the converse, if $T \subseteq \{a\} \cup S$ then we can find T_1 and T_2 in $\mathcal{F}X$ such that $T = T_1 \cup T_2, T_1 \subseteq \{a\}$ and $T_2 \subseteq S$. If $T_1 = \emptyset$ then $T = T_2 \subseteq S$, while if T_1 is inhabited then it is $\{a\}$ and so $T = \{a\} \cup T_2$ with $T_2 \subseteq S$.

The following proposition is included not for its general importance, but because it is used later on (in Section 4.4) at a point where one might more naturally expect to use the set of functions from S to T . However, for finiteness of the set of functions we should require decidability of S so that single valuedness of a relation R could be expressed as $\forall (x, y), (x, y) \in R \; (x \neq x \; \lor \; y = y)$. If S is finite, then we define a *finite total relation* from ^S to ^Y to be ^a nite relation ^R n ^S - Y satisfying 8x ² S:9y ² Y :(x; y) ² R.

Lemma 2.1.10. If S and T are finite, then so is the set $FT(S, T)$ of finite total relations from S to T .

Proof. If X and Y are types then we desire FT : FX - FY ! FF(X - Y) such that

 $\mathbb{P} \mathbf{v} = \mathbf{v} \cdot (\mathbf{v}^T \mathbf{v}) = \mathbf{v} \cdot \mathbf{v} \cdot \mathbf{v}$. The set of $\mathbf{v} \cdot \mathbf{v} = \mathbf{v} \cdot (\mathbf{v} \cdot \mathbf{v})$

We define FT to be the unique function such that

FT(
$$
\emptyset
$$
, T) = { \emptyset }
FT({ a } \cup S , T) = { $R \cup \{a\} \times T'|R \in FT(S, T) \land T' \in \mathcal{F}_1(T)$ }

Again, it is not hard to show that this definition satisfies the conditions for $\mathcal{F}\text{-recursion}$.

When S = ; we have R ² FT(;; T) , R = ; , R ; - T ^ 8x ² ;:9y ² T :(x; y) ² R as required. For the other case,

$$
R \in \text{FT}(\{a\} \cup S, T)
$$

\n
$$
\Leftrightarrow \exists R', T'. (R' \in \text{FT}(S, T) \land T' \in \mathcal{F}_1(T) \land R = R' \cup \{a\} \times T')
$$

\n
$$
\Leftrightarrow \exists R', T'. (R' \subseteq S \times T \land \forall x \in S. \exists y \in T. (x, y) \in R'
$$

\n
$$
\land T' \in \mathcal{F}_1(T) \land R = R' \cup \{a\} \times T')
$$

This certainly implies that R (fag [S) - T and 8x ² fag [S:9y ² T :(x; y) ² R. For the converse, from R (fag [S) - T = fag - T [S - T we deduce that there are nite R1 and R1 α such that R α , R1 α R1 α , α , α is the canonic binary can be can be called that $(a, b) \in R$; let $R_1 = R_1 \cup \{(a, b)\} \subseteq \{a\} \times I$. If T is the direct image of R_1 under the projection to T then $T \in \mathcal{F}_1(T)$ (imhabited because it comtains v), and $R_1 = \{u\} \times T$. Next, R_2 in itself might not be enough for R_0 (in the case where $a \in S$). However, we have $\forall x \in S. \exists y \in I$ $(x, y) \in R$ and so by Theorem 2.1.0 (6) there is some $R_2 \subseteq_{fin} R$ such that ist $(n_2) = S$. Let $R_1 = n_2 \cup n_2$, we have that $R_2 \subseteq S \times I$, $\forall x \in S$. $\nexists y \in T$, $(x, y) \in R$, and $R = R \cup \{a\} \times I$, so we have found R and T as required.

We finish this section by strengthening the principle of $\mathcal{F}\text{-induction considerably}$, strengthening the induction hypothesis. (The only place where we need the stronger principle is in our account of Abramsky's normalization result for function spaces, our Lemma 4.4.5.)

Theorem 2.1.11. (The principle of strong F-induction) Let $P \subset \mathcal{F}X$ be a predicate satisfying the induction step $-$

$$
\forall x \in S. \exists U : \mathcal{F}X. (S = \{x\} \cup U \land P(U)) \vdash_{S: \mathcal{F}X} P(S) \quad (*)
$$

Then P satisfies

$$
\vdash_{S:\mathcal{F}X} P(S)
$$

Proof. Because emptiness of a finite set is decidable, the induction hypothesis (the premiss of (*)) implies $S = \emptyset \vee \exists x : X.\exists U : \mathcal{F}X.(S = \{x\} \cup U \wedge P(U)),$ which is a collected form of induction hypothesis for simple \mathcal{F} -induction. It follows that this is a formally stronger induction principle: any proof that uses the simple induction principle can easily be turned into a proof using strong induction.

The proof of validity of the strong principle is by induction on the size n of a representation $S = \{x_1, \ldots, x_n\}$ (possibly with repetitions amongst the x_i s - in the absence of decidable equality there is no well-defined cardinality of S), and one role of the Theorem is to package up such induction and give a reasoning principle that does not have to refer to the representation. I am grateful to Paul Taylor for a discussion that led to a rigorous proof along these lines to replace a more complicated one that I originally had.

Let us write βX for the free commutative monoid over X. One should think of its elements as the finite bags, or multisets, over X. We write $+$ (bag sum) and 0 (empty bag) for the monoid operation and its unit, and $\{-\}$ for the injection of generators (so $\{x\}$ is the singleton bag containing x). We also write $\# : BX \to \mathbb{N}$ for the monoid homomorphism with $\#\{x\} = 1$ (so $\#B$ is the total size of B), and $\sigma : BX \to FX$ for the monoid homomorphism with $\sigma\{|x\} = \{x\}$ (so σB is the set of elements of B).

It is straightforward to prove the following induction principle on $\mathcal{B}X$: if $P \subset \mathcal{B}X$ is such that $P(0)$, and whenever $P(B)$ then $P(\lbrace x \rbrace + B)$, then $P(B)$ holds for all B. We can now show $-$

- 1 If $#B = 0$ then $B = 0$ (easy by bag induction)
- 2 σ is onto: for the image of BX is a submonoid of FX that contains all the generators ${x}.$
- 3 If $x \in \sigma B$ then there is some C such that $B = \{x\} + C$. The base case, $B = 0$, is obvious $-x \in \sigma$ U is impossible. If $x \in \sigma(\{|y|\} + B) = \{y\} \cup \sigma B$, then either $x = y$ or $x \in \sigma$ B ϵ in $x = y$, then $\{y\}\rightarrow \epsilon$ B ϵ = $\{x\}\rightarrow \epsilon$ is $x \in \sigma$ B, then by induction $B_0 = \{ |x|_1 + C_0 \text{ for some } C_0, \text{ so } \|y\|_1 + B_0 = \{ |x|_1 + C_0 \}$.

Now let P be as stated in the overall theorem. It suffices to show $\forall n : \mathbb{N} \cdot Q(n)$, where

$$
Q(n) \equiv_{\text{def}} \forall B : BX. (\#B = n \to P(\sigma B))
$$

When $n = 0$, we have $P(\emptyset)$ because the induction hypothesis holds vacuously. Otherwise, suppose $\#D = n + 1$. If $x \in \sigma D$ then $D = \{x \mid r + D\}$ for some D , and $\#D = n$. By

induction on *n* we have $P(\sigma D)$, and $\sigma D = \{x \} \cup \sigma D$. It follows from (*) that $P(\sigma D)$ as required.

2.2. The 2-category Top of toposes

We shall describe here some aspects of categorical structure of the category Top of toposes (Grothendieck toposes with geometric morphisms between them) and of its slices Top/B. Though the constructions are well known, we shall need to describe them in t terms of the theories classified $-$ in effect, in terms of the points of the toposes.

It is worth bearing in mind that **Top** is in fact a 2-category: each hom-class $\text{Top}(D, E)$ is a category, and a large one at that (though locally small). As a consequence, it is generally too much to expect diagrams in Top to commute "on the nose", i.e up to equality ${\rm -commuting}$ is usually only up to isomorphism. In broad terms, this is because in a category equality between ob jects is less important that isomorphism. Moreover, universal properties should properly be described in a 2-categorical form. For instance a product D - E is a representing ob ject for a functor from Top to Cat, taking a topos F $\mathcal{L} \mathcal{L} \mathcal{$ the functor from Top(F; D-E) to Top(F; D)-Top(F; E), mapping f to (f ; fst; f ; snd), is an equivalence of categories.

We shall need to work not only in Top itself, but also in the slice categories Top/B . The 2-categorical laxness that we shall allow is that the morphisms, triangles in which two sides have common target B , are to commute up to a given isomorphism. An important issue will be whether the constructions we describe are preserved by the pullback functors between slice categories: in fact, they all are.

2.2.1. Terminal object The terminal topos 1 classifies the empty theory (no vocabulary, no axioms). $S1 = Set$.

2.2.2. Pullbacks Let D and E be two toposes over a base B : in other words we are given geometric morphisms $f: D \to B$ and $g: E \to B$. To avoid having to name too many things, we shall use restriction map notation so that (for instance) if x is a point of D then $x|_B = f(x)$.

The pullback \equiv \cdots μ \equiv . And the points of μ \cdots μ are μ and μ and μ and μ and μ and θ : $x|_B \cong y|_B$.

This construction covers pullbacks and binary products in slices Top/C .

2.2.3. Comma squares Again let D and E be toposes over B. The comma object $D > B$ E classifies triples (x, y, θ) where x and y are points of D and E, and $\theta : x|_B \to y|_B$ is a homomorphism. Again this covers comma squares in slices. A particular case of this is the *inserter*, when a single topos D lies over B in two different ways $f, g : D \to B$. The comma object $(D, f) > B(D, g)$ is the inserter for f to g.

2.2.4. Initial object The initial topos \emptyset classifies the contradictory theory (no vocabulary, axiom true \vdash false). To see why, suppose we have a point of \emptyset , in other words we have

contradiction false. Then any interpretation of vocabulary will give a model for any theory, and any two interpretations will be isomorphic. The same topos \emptyset is initial in every slice, and is preserved by pullback.

2.2.5. Bagtoposes If D is a topos, then there is also a topos $B_L D$, its lower bagtopos, whose points are pairs $(S, (x_{\lambda})_{\lambda \in S})$ where S is a set and $(x_{\lambda})_{\lambda \in S}$ is an S-indexed family of points of D. In terms of geometric theory presentations, the slightly intricate construction involves adding a new sort (for S) and functions from the old sorts to S in such a way that the fibres over elements of S are models of the old theory. This can be universally characterized as a partial product (Johnstone 1992); it is a notable example of a case where care is needed in giving a proper 2-categorical account of the universal property (Johnstone 1993). We shall not go into the details here but use these construction mainly to make geometric sense of phrases such as "set-indexed family of points".

2.2.6. Coproducts Let D and E be toposes. Then their coproduct $D+E$ classifies tuples

$$
(I,(x_{\lambda})_{\lambda\in I},J,(y_{\mu})_{\mu\in J},\theta)
$$

where $(x_{\lambda})_{\lambda \in I}$ is an *I*-indexed family of points of D, $(y_{\mu})_{\mu \in J}$ is a *J*-indexed family of points of E, and $\theta: I + J \cong 1$. (Classically, of course, this is either a point of D or a point of E .)

We write it this way to make it clear using bagtoposes that we have a geometric theory, but in practice we can use a more perspicuous notation. The subsingletons I and J with $I + J \cong 1$ are equivalent to a Boolean value (complemented proposition) $p \equiv \exists \lambda \lambda \in I$, and the I- and J-indexed families are equivalent to a point x of D defined if p , and a point y of E if $\neg p$. Let us therefore write this point of $D+E$ as a conditional if p then x else y. The injection inj₁ : $D \to D + E$ maps x to **if true then** x **else** –, and inj₂ maps y to if false then $-$ else y.

An important feature of the if \dots then \dots else \dots notation is that it embodies a filtered diagram. Consider if p then u else v, where u and v are points of a single topos. This gives a diagram whose shape is the discrete category $\{*\in 1 \mid p\} + \{*\in 1 \mid \neg p\} \cong 1$, and whose nodes are u for each $*$ in $\{*\in 1 \mid p\}$ and v for each $*$ in $\{*\in 1 \mid \neg p\}$. The diagram is filtered and hence has a colimit (another point of the same topos). We shall write "if p then u else v " to denote this filtered colimit.

To see that $D + E$ is a coproduct, consider maps $f : D \to F$ and $g : E \to F$. A point $u =$ if p then x else y of $D + E$ is isomorphic to the filtered colimit

if p then (if true then x else-) else (if false then – else y)

 $=$ if p then inj₁ x else inj₂ y

Because geometric morphisms preserve filtered colimits of points, the copairing $[f, g]$ has to map u to the colimit of the image diagram in F, namely if p then $f(x)$ else $g(y)$.

(The alert reader may well be worried by this recourse to preservation of ltered colimits when the diagrams are not external ones, but in fact sense can be made of the argument.)

If D and E are toposes over B, then $D + E$ is still the coproduct in Top/B . Moreover, If $f: C \to B$, then $f_-(D+E)$ is equivalent to f_+D+f_-E . A point of f_-D+f_-E is of the form if p then (x, z, φ) else (y, z, ψ) where x and y are points of D and E, z and z are points of U, $\varphi : f(z) = x|_B$ and $\psi : f(z) = y|_B$. If we let $z =$ if p then z eise z, then (if p then x else y), z, σ) is a point of $f(D + E)$, σ being the isomorphism

```
f(z) = f(\text{if } p \text{ then } z \text{ else } z) \cong \text{if } p \text{ then } f(z) \text{ else } f(z)\cong if p then x|_B else y|_B = (if p then x else y|_B)
```
I ms gives an equivalence between $f \, D + f \, E$ and $f \, (D + E)$.

2.2.7. Exponentials Top is not Cartesian closed. However, many of the toposes we shall be dealing with are exponentiable, so exponentials often exist. Let us note a general 2-categorical fact, that pullback functors between slices preserve existing exponentials. For suppose $q : E \to B$ is a geometric morphism and that D_1 and D_2 are toposes over B such that the exponential $D_1 \Rightarrow_B D_2$ in Top/B exists. If F is a topos over E, then the following kinds of maps are all equivalent:

$$
F \rightarrow q^*(D_1 \Rightarrow_B D_2) \text{ over } E
$$

\n
$$
F \rightarrow D_1 \Rightarrow_B D_2 \text{ over } B
$$

\n
$$
F \times_B D_1 \rightarrow D_2 \text{ over } B
$$

\n
$$
F \times_E q^* D_1 \rightarrow D_2 \text{ over } B \text{ (because } F \times_E q^* D_1 \cong F \times_B D_1)
$$

\n
$$
F \times_E q^* D_1 \rightarrow q^* D_2 \text{ over } E
$$

It follows that $q_1 \cup_1 \Rightarrow_B D_2$) is an exponential $q_1 \cup_1 \Rightarrow_E q_2$.

2.3. Lifting in Top

It is convenient to summarize here general results about lifting of toposes, commonly known as scone or Freyd cover (Johnstone and Moerdijk 1989; Johnstone 1992). Some of the coherence questions that arise are quite intricate, and we shall defer detailed discussion of them (in more general 2-categories than Top) to a later study. Here we shall be content with sketching the concrete constructions.

Definition 2.3.1. (Johnstone and Moerdijk 1989) A topos D is local iff the unique (up to isomorphism) map ! : $D \to 1$ has a left adjoint $\bot : 1 \to X$ (\bot pronounced "bottom"). Being a left adjoint means exactly that the global point \perp is initial amongst all points: if $f: Y \to X$, then there is a unique 2-cell from $\vdots \perp$ to f.

(Clearly this definition can be extrapolated to general 2-categories. In particular, in posetenriched categories, \perp is indeed a bottom point of D and so we use this term rather than Johnstone and Moerdijk's "centre" which seems topographically wrong.)

A map between two local toposes is *strict* iff it preserves \perp (up to isomorphism).

We now have a sub-2-category \bf{LTop} of \bf{Top} , full on 2-cells, whose objects and morphisms are the local toposes and strict maps.

We shall feel free to extend these definitions to slice categories Top/B by change of base, getting the notions of toposes or maps being local or strict over B.

The essence of *lifting* is that it provides a left adjoint to the inclusion $\text{LTop} \rightarrow \text{Top}$ $-$ this is exactly what lifting of domains does in a rather simpler context. It is less straightforward in our 2-categorical context, but Johnstone (1992) shows that the scone or Freyd cover construction has the right properties. In Johnstone and Moerdijk (1989), $\mathcal{L}X$ is written X.

Definition 2.3.2. Let X be a topos over base B . (We shall use restriction notation for the map from X to B.) The scone or lifting of X over $B, \mathcal{L}_B X$, classifies triples $(b, I, (x_{\lambda}, \theta_{\lambda})_{\lambda \in I})$ where b is a point of B, I is a subsingleton, and $(x_{\lambda}, \theta_{\lambda})_{\lambda \in I}$ is an Iindexed family of pairs, x_{λ} a point of X and $\theta_{\lambda} : x_{\lambda}|_B \cong b$. This is again a topos over B, by the map that forgets everything except b.

Over B, it has an initial point given by $b \mapsto (b, \emptyset, (-,-))$, and a map up : $X \to \mathcal{L}_B X$ given by $x \mapsto (x|_B, 1, (x, id))$. Note that the point $(b, I, (x_{\lambda}, \theta_{\lambda})_{\lambda \in I})$ of $\mathcal{L}_B X$ is a filtered colimit of $\bot(b)$ and points up(x_λ).

Proposition 2.3.3. \mathcal{L}_B provides lifting in Top/B.

Proof. This and further properties of lifting (e.g. that it has coKZ properties) follow from the fact that $\mathcal{L}_B X$ is a cocomma object in Top:

$$
\begin{array}{ccc}\nX & \longrightarrow & B \\
\text{Id} & \downarrow & \downarrow & \downarrow \\
X & \longrightarrow & \mathcal{L}_B X \\
\end{array}
$$

(The morphism up is the unit of the monad \mathcal{L}_B .)

We now turn to discuss the axiomatization by Crole and Pitts (1992) of lift. They require a structure and \mathbf{r}_i is an \mathbf{r}_i , and it is a global point in the second point in the contract of the second second contract in the second second up; : ! . However, \algebra" here is used in a sense that is weaker than that of Eilenberg-Moore algebra for lift qua monad, so let us avoid confusion by using the word structure for the weaker sense.

Definition 2.3.4. Let $F: C \to C$ be an endofunctor of a category C. Then an F structure is an object X of C equipped with a morphism $a: FX \to X$.

Theorem 2.3.5. Each slice Top=B has a xpoint-ob ject B - Idl(N).

(Note that in the 2-category Top even the statement of this theorem raises coherence questions that we are neglecting for the time being.)

 $\mathbf P$ rst prove the case when $\mathbf P$ initial segments of N (so it is the ideal completion of (N),)). It is local (Its initial points is four and we also have a map such that α is the four α function α four α four α four α the universal property of L, extends to : ^L ! .

 \mathbf{u} if we define the global point \mathbf{u} if whole point \mathbf{u} is the whole point \mathbf{u} of N, then this is the equalizer for Id and up; $\sigma = \text{succ}$. For if $S = \text{succ}(S)$ then $0 \in S$ and n is the 1 2 S for every non-terminal point of \mathcal{S} . Notice that is a natural point of \mathcal{S} is a natural point of \mathcal{S} . In the set of \mathcal{S} is a natural point of \mathcal{S} is a natural point of \mathcal{S} is

Now suppose $F : \mathcal{L}D \to D$ is a structure for \mathcal{L} . We require an essentially unique $\lim_{\mu \to \infty} \mu(x)$, $\mu \to \nu$ that is an μ -structure homomorphism, in other words σ , $\mu(T) =$

 $\mathcal{L}(\text{it}(F))$; F. Now an ideal S of N is a filtered colimit of the principal ideals $\downarrow n$ such that $n \in S$, so the action of it(F) is determined by its action on principal ideals and the inclusions between them. We have $-$

$$
it(F)(\downarrow 0) = it(F) \circ \sigma(\perp) \cong F \circ \mathcal{L}(it(F))(\perp) = F(\perp_{\mathcal{L}D})
$$

$$
it(F)(\downarrow (n+1)) = it(F) \circ \text{succ}(\downarrow n) = it(F) \circ \sigma \circ \text{up}(\downarrow n)
$$

$$
\cong F \circ \mathcal{L}(it(F)) \circ \text{up}(\downarrow n) \cong F \circ \text{up} \circ it(F)(\downarrow n)
$$

By induction, this proves uniqueness of it(F) on principal ideals. Let us write x_n for it $(F)(\downarrow n)$.

$$
it(F)(\downarrow 0 \sqsubseteq \downarrow 1) = it(F) \circ \sigma(\perp \to up(\downarrow 0))
$$

$$
\cong F \circ \mathcal{L}(it(F))(\perp \to up(\downarrow 0))
$$

$$
= F(!: \perp \to up(x_0))
$$

$$
it(F)(\downarrow (n+1) \sqsubseteq \downarrow (n+2)) = it(F) \circ \sigma \circ up(\downarrow n \sqsubseteq \downarrow (n+1))
$$

$$
\cong F \circ up \circ it(F)(\downarrow n \sqsubseteq \downarrow (n+1))
$$

This proves uniqueness of it(F) on inclusions between principal ideals, and hence (taking ltered colimits) on arbitrary points of . It also proves existence by allowing us to dene it $(F)(S)$ as the filtered colimit of the corresponding diagram (over $n \in S$) of points of D.

The argument for Top/B is similar, but parametrized by points of B. The fixpoint , and the $\mathcal{L}=\mathcal{L}$ is an IdB - \mathcal{L} - \mathcal{L} - \mathcal{L} , \mathcal{L} and \mathcal{L} - \mathcal{L} , $\mathcal{L$ (using the fact that $\mathcal{L}_B(D \times \mathcal{U}) = D \times \mathcal{L}(\mathcal{U})$.

We use the fixpoint object to prove a remarkable property of local toposes, namely that they are exactly the topical analogues of Freyd's (1991) algebraically complete categories, i.e. those for which every endofunctor has an initial structure. By considering the identity endofunctor one can prove that every algebraically complete category has an initial object, but the converse is far from true. However, we show that if a topos D has an initial point (that is to say, it is local), then every endomap F has an initial structure - it is constructed using filtered colimits of points. To make this precise, we consider the topos $[F\text{-Str}]$ that classifies F-structures. (An F-structure is a point x of D equipped with a homomorpism $\alpha : Fx \to x$. This is the inserter for F to Id_D.

We first set out some easy facts about toposes $[F-Str]$ that are familiar from the category context (Freyd 1991).

Proposition 2.3.6. Let F be an endomap of a topos D .

- 1 Let α : $Fx \rightarrow x$ and β : $Fy \rightarrow y$ be two *F*-structures. Then homomorphisms from α to β are homomorphisms $f: x \to y$ such that $\alpha; f = Ff; \beta$.
- 2 r extends to an endomap of $[r$ -Str), mapping α : $rx \rightarrow x$ to $r\alpha$: r $x \rightarrow rx$. Moreover, there is a natural transformation from this F to $Id_{[F_{\text{est}}]}$.
- 3 If [F-Str] is local, with initial point α : $Fa \to a$, then α is an isomorphism.

Proof. 1. This is quite obvious. (The issue is that the general notion of homomorphism between models of a geometric theory has already been defined.)

2. Also obvious. α itself provides the homomorphism from Fx to x.

3. We briefly recall the usual argument. By initiality there is a unique F -structure homomorphism $\alpha : a \to ra$. The composite $\alpha : \alpha$ is the unique r -structure endomorphism on a , and so is equal to the identity. Then because α is an r -algebra homomorphism we have $\alpha; \alpha = F \alpha$; $F \alpha = F (\alpha; \alpha) = F (\alpha_a) = \alpha_{Fa}$.

Proposition 2.3.7. Let D and E be toposes, and $F : D \to E$ and $G : E \to D$ maps. Then $[GF-Str]$ is local iff $[FG-Str]$ is.

Proof. Suppose [GF-Str] is local, with initial point α : GFa \rightarrow a. By an obvious generalization of Proposition 2.3.6 (2), F and G extend to maps $F : [GF-Str] \rightarrow [FG-$ Str] and $G : [FG\text{-Str}] \rightarrow [GF\text{-Str}]$; we show that $F\alpha$ is an initial point of $[FG\text{-Str}]$. Suppose that β : $FGy \rightarrow y$ is an FG-structure, and let $f : a \rightarrow Gy$ be the unique GF-structure homomorphism. Then Ff ; β : $Fa \rightarrow y$ is an FG-structure homomorphism. For uniqueness, let $g : Fa \rightarrow y$ be another. Then $\alpha = \bigcup g : a \rightarrow Gy$ is the unique GF structure nomomorphism and so equals f. Then $F(f; p = F\alpha^{-1}; F \cup q; p = F\alpha^{-1}; F \alpha; q =$ g \blacksquare

Theorem 2.3.8. (In Top, local \iff **algebraically complete)** Let D be a topos. Then D is local iff for every map $F: D \to D$, $[F-Str]$ is local.

Proof. (Again, in the proof here we are neglecting coherence issues.)

 \Leftarrow : Take $F = \text{Id}_D$, and let $\alpha : a \to a$ be the initial point in [Id-Str]. There is a unique Id-structure homomorphism from (a, α) to itself, i.e. a unique homomorphism $f : a \to a$ such that α ; $f = f$; α . But both Id_a and α satisfy this, so $\alpha = Id_a$. Now by considering the unique Id-structure homomorphism from (a, Id_a) to (b, Id_b) , we see that there is a unique homomorphism from a to any point b of D . Hence D is local with initial point a .

 \Rightarrow : Let us write S for the topos [F-Str]. By Proposition 2.3.3, we have a unique strict map $F : L D \to D$ such that up; $F = F$, and hence $\mathfrak{u}(F) : M \to D$ the unique L structure homomorphism. Let $a = \iota(r / \sqrt{\omega})$. Then

$$
a = \operatorname{it}(F') \circ \sigma \circ \operatorname{up}(\omega) \cong F' \circ \mathcal{L}(\operatorname{it}(F')) \circ \operatorname{up}(\omega) \cong F' \circ up \circ \operatorname{it}(F')(\omega) = F(a)
$$

and the isomorphism makes a an F-structure $A = (\alpha : Fa \rightarrow a)$. This will be our initial point \perp of S.

Now let E classify diagrams of the form $Fb \leftrightarrow b \leftrightarrow y$ where b and y are points of D, and β and f are homomorphisms. E is a topos over S (by the map that picks out the structure $\beta : Fb \to b$, and moreover it is local over S: the initial point over the algebra b has $y = \bot$. We can define a map $G : E \to E$ over S mapping the above diagram to

$$
Fb \stackrel{\beta}{\longrightarrow} b \stackrel{\beta}{\longleftarrow} Fb \stackrel{Ff}{\longleftarrow} Fy
$$

From G we get a map $G^-: LSL \to E$, strict over S. The forgetful map from E to S \times D (forgets f) is an \mathcal{L}_S -structure homomorphism, and so we have a diagram of \mathcal{L}_S -structures

$$
S \times \Omega \qquad \xrightarrow{\text{Id} \times \text{it}(F')} \qquad S \times D
$$

||

$$
S \times \Omega \qquad \xrightarrow{\longrightarrow}_{\text{it}(G')} E \qquad \longrightarrow \qquad S \times D
$$

Forget

By initiality of $S \times \Omega$, it follows that for an F-structure $D = (\beta : F \theta \rightarrow \theta),$ it $(G^{\prime}) (D, \omega)$ has the form $Fb \to b \leftrightarrow a$. By the equalizing property of ω , we have an isomorphism

$$
\begin{array}{ccc}\nFb & \stackrel{\beta}{\longrightarrow} & b & \stackrel{g}{\longleftarrow} & a \\
\parallel & & \parallel & & \uparrow \alpha \\
Fb & \stackrel{\longrightarrow}{\beta} & b & \stackrel{\longleftarrow}{\longleftarrow} & Fb \stackrel{\longleftarrow}{\longleftarrow} & Fa \\
 & & \downarrow \beta\n\end{array}
$$

so that g is an F -structure homomorphism.

To prove uniqueness, let S_1 classify F-structures $\beta : Fb \to b$ equipped with F-structure homomorphisms $h : a \to b$, and let E_1 classify points of S_1 equipped with homomorphisms $f: y \to b$. E_1 is local over S_1 (take $y = \perp$). We have a map $G_1: E_1 \to E_1$ over S_1 , defined just like G, and hence $G_1: \mathcal{L}_{S_1}E_1 \to E_1$. Define a map $H: S_1 \times M \to E_1$ by letting $H((B, h), n)$ be (B, h) equipped with

$$
it(F')(n \sqsubseteq \omega); h : it(F')(n) \rightarrow it(F')(\omega) = a \rightarrow b
$$

We show that H is an \mathcal{L}_{S_1} -structure homomorphism, so we check that two maps agree on $\mathcal{L}_{S_1}(S_1 \times \mathcal{U}) = S_1 \times \mathcal{L}\mathcal{U}$ – they are $(S_1 \times \sigma);$ H and $\mathcal{L}_{S_1}H;$ G_1 . Since every point of , and it such that the collimit of points \mathcal{L} and \mathcal{L} points to check on the check on the set of \mathcal{L} $((B,h), \perp)$, we find that both images in E_1 have homomorphisms $\perp \to b$ which must be equal by initiality of \perp in D. For $((B, h), n)$, we find that the two images are given by the following two homomorphisms to b :

$$
\operatorname{it}(F')(suc n) \xrightarrow{\operatorname{it}(F')(suc n \sqsubseteq \omega)} a \xrightarrow{h} b
$$

$$
F \circ \operatorname{it}(F')(n) \xrightarrow{F \circ \operatorname{it}(F')(n \sqsubseteq \omega)} F a \xrightarrow{Fh} F b \xrightarrow{\beta} b
$$

To show these are isomorphic, consider the diagram:

$$
\begin{array}{rcl}\n\text{it}(F')(suc\ n) & \stackrel{\cong}{\longleftarrow} & F' \circ \mathcal{L}\, \text{it}(F') \circ \text{up}(n) & \stackrel{\cong}{\longleftarrow} & F \circ \text{it}(F')(n) \\
\text{it}(F')\, \text{su}(n\sqsubseteq\omega) \downarrow & \downarrow_{F' \circ \mathcal{L}\, \text{it}(F') \circ \text{up}(n\sqsubseteq\omega)} & \downarrow_{F \circ \text{it}(F')(n\sqsubseteq\omega)} \\
\text{it}(F')(suc\ \omega) & \underset{\cong}{\longleftarrow} & F' \circ \mathcal{L}\, \text{it}(F') \circ \text{up}(\omega) & \underset{\cong}{\longleftarrow} & F \circ \text{it}(F')(n\sqsubseteq\omega) \\
& & & & & \\
\downarrow & & & & & \\
\downarrow & & & & & \\
a & & & & & \\
b & & & & & \\
b & & & & & \\
\end{array}
$$

Here, the bottom part commutes because h is an F -structure homomorphism, the middle part by definition of a , the top right because up is a natural transformation from Id to \mathcal{L} , and the top left because $\iota(r \to s \text{ is an } \mathcal{L}$ -structure homomorphism.

 \sim

This shows that H is an \mathcal{L}_{S_1} -structure homomorphism (hence the unique one) from $S_1 \times M$ to E_1 . But there is another H , defined by $H((B, n), n) = \text{lt}(G_1(B, n))$ with n tacked on, and so $H = H$. Applying them both to $((D, h), \omega)$, we see that $h = g$ and hence there is a unique F-structure homomorphism from A to B. \blacksquare

Corollary 2.3.9. Let D be an arbitrary topos, $F : \mathcal{L}D \to D$ a map. Then $[(\text{up}; F)$ -Str is local.

Proof. $\mathcal{L}D$ is local, so by Theorem 2.3.8 $[(F; up)-Str]$ is local. Now apply Proposition

2.4. Algebraic dcpos

The localic theory of algebraic dcpos is well-known, but we shall recall some of it here for three reasons.

- 1 The strongly algebraic domains that are the main concern of this paper are algebraic dcpos, and many of the points discussed here will be needed later in the special case.
- 2 They provide a simple example to illustrate the \Display categories" in Section 3.2.
- 3 We wish to illustrate the idea that a locale is a special kind of topos.

Let us first recall the localic theory of algebraic dcpos.

Definition 2.4.1. Let X be a poset. We define its *ideal completion* Idl X to be the locale whose points are the ideals of X (the directed lower-closed subsets).

A locale is an *algebraic dcpo* iff it is homeomorphic to Idl X for some poset X .

Certainly the theory of ideals of X is geometric; it is most conveniently presented using a unary predicate $I \subseteq X$ satisfying -

$$
I(t) \wedge s \sqsubseteq t \vdash_{st} I(s)
$$

true $\vdash \exists s. I(s)$

$$
I(s) \wedge I(t) \vdash_{st} \exists u. (I(u) \wedge s \sqsubseteq u \wedge t \sqsubseteq u)
$$

Since the theory has no new sorts, it is essentially propositional and Idl X is a locale (more precisely, it is localic relative to the theory where X lives).

The familiar results on algebraic dcpos are constructive, and hold in a general geometric universe.

Proposition 2.4.2. Let X be a poset. Then the following frames are isomorphic:

$$
1 \quad \Omega \operatorname{Idl} X
$$

2 Fr $\{\uparrow s \ (s \in X) \mid \uparrow t \leq \uparrow s \ (s \sqsubseteq t)\}$

$$
\mathbf{true} \leq \bigvee_{s \in X} \uparrow s
$$

$$
\uparrow s \wedge \uparrow t \leq \bigvee \{\uparrow u : u \in X, s \sqsubseteq u, t \sqsubseteq u\}\big)
$$

- The Alexandroff topology Alex X on X (that is to say, the frame of upper-closed $\mathbf{3}$ subsets of X).
- 4 The Scott topology on the set of ideals of X.

Proposition 2.4.3. A locale is an algebraic dcpo iff its frame is the Scott topology of a set-theoretic dcpo D satisfying one of the following equivalent conditions:

1 D is order-isomorphic to the set of ideals of the poset KD of its compact elements.

2 Every element of D is a directed join of compact elements below it.

Then its global points are in order-isomorphism with D.

However, neither the frame nor the set-theoretic ideal completion is geometric, so these constructions are less important to us.

If we consider the generic poset (X, \subseteq) in S[poset], we obtain its ideal completion Idl X as a locale [poset][ideal] over [poset], and every algebraic dcpo (over any topos) is a

pullback of it. (We are extending the notation of Section 1.1 by writing [poset][ideal] for the topos that classifies pairs (X, I) , X a poset and I an ideal of it.) We may therefore consider [poset][ideal] \rightarrow [poset] as the *algebraic dcpo classifier*. "Classifier" here has the same sense as in "subobject classifier", not as in "classifying topos". In an elementary topos, the subob jects are the pullbacks of the subob ject classier true : 1 ! , and in the category of toposes the algebraic dcpos are the pullbacks of the algebraic dcpo classifier.

To summarize: The ideal completion of a poset can be constructed "generically", as a geometric morphism [poset][ideal] \rightarrow [poset]. All other instances of the construction, over any topos, can be obtained from this one as pullbacks.

An important corollary from these results is that algebraic dcpos are exponentiable in the category of toposes (Lemma 4.1 of Johnstone and Joyal (1982)). Of course, it is better known that they are exponentiable in the category of locales, i.e. locally compact. The corresponding property for toposes is slightly stronger $-$ such locales are known as "metastably locally compact" $-$, but the results of Johnstone and Joyal are enough to show that it holds for algebraic dcpos.

If X and Y are posets, then by analysing the frame homomorphisms from Fr $(\uparrow s)$ $(s \in X) \mid \dots$ to Alex X one easily sees that continuous maps from Idl X to IdlY can be described equivalently as certain relations f from X to Y – explicitly, they are those relations satisfying $-$

$$
s' \supseteq s f t \supseteq t' \vdash_{s' s t t'} s' f t'
$$

true $\vdash_s \exists t \in Y. s f t$
s f t₁ \wedge s f t₂ $\vdash_{s t_1 t_2} \exists t \in Y.(s f t \wedge t \supseteq t_1 \wedge t \supseteq t_2)$

Such relations are known as *approximable mappings* from X to Y . The identity approximable mapping is \exists , and composition is by relational composition.

Note that the last two axioms are the nullary and binary case of a more general form that can be proved from the special cases by induction on n .

$$
\bigwedge_{i=1}^n s f t_i \vdash \exists t.(s f t \land \bigwedge_{i=1}^n t \sqsupseteq t_i)
$$

We can state this more succinctly using finite sets: if T is a finite subset of Y , then

$$
\forall t' \in T \, s \, f \, t' \vdash \exists t \, (s \, f \, t \land \forall t' \in T \, t \supseteq t')
$$

Note also that approximable mappings are geometric in the sense that there is a geometric theory whose models are pairs (X, Y) of posets, together with an approximable mapping (appearing as a binary predicate) between them. Let us write AM for this theory. There are then two posets X_s and X_t in $\mathcal{S}[\text{AM}]$, i.e. two geometric morphisms from [AM] to [poset], so [AM] is a topos over [poset]. Thinking spatially, the libre over a given pair of posets is to be the space of continuous maps from $\text{Id}(X_s)$ to $\text{Id}(X_t)$, so perhaps [AM] should be the exponential $\text{IdI}(X_s) \Rightarrow_{[\text{poset}]^2} \text{IdI}(X_t)$ over [poset]. Indeed it is.

Theorem 2.4.4. The exponential $(\text{Idl}(X_s) \Rightarrow_{[\text{poset}]^2} \text{Idl}(X_t))$ exists and classifies the theory AM.

Proof. This is an application of Lemma 4.1 in Johnstone and Joyal (1982). Let us sketch the proof in this simple case. If D is a topos over [poset], then let X and Y be the two corresponding posets in SD . It can be calculated that Idl(X) classifies the theory of pairs (x, F) where x is a point of D and F is a flat presheaf on $X(x)$: hence by Diaconescu's theorem, $\mathcal{S} \text{Idl}(X)$ is equivalent to the geometric universe of internal X-diagrams in SD. A geometric morphism from $\text{Idl}(X)$ to $\text{Idl}(Y)$ is an ideal of the constant internal X-diagram corresponding to Y , but this can be calculated to be just an approximable mapping from X to Y. \blacksquare

This result gives us a universal characterization of the topos [AM] that does not depend on the presentation we gave for the theory AM.

3. Examples of topical categories

3.1. Intrinsic categories

An important aspect of the 2-categorical structure of Top is that it allows us to imagine each topos $D = [T]$ as a category – not as its geometric universe SD , but as an idealization of pt D (i.e. $\text{Top}(1, D)$) that transcends the possible insufficiency of models of T in Set.

The way this works as a practical technique is that if you have an aspect of categories that can be expressed using the 2-categorical structure of Cat , then that expression can be translated to Top. For instance, a category C has an initial object iff the unique functor ! : $C \rightarrow 1$ has a left adjoint. Transferring this property to **Top** gives a natural notion of "topos with initial point" (and these are the local toposes of Section 2.3). C nas innite coproducts in every diagonal functor $\Delta_n : C \to C^+$ has a felt adjoint, and in Top we get the notion of "topos with all finite coproducts". A result of Johnstone's (1992) can then be naturally read as saying that a certain bagdomain construction freely adjoins finite coproducts to a topos.

This somewhat mystical category of generalized points is manifested as a topical category, because if T is a geometric theory then the theory of two models with a homomorphism between them is also geometric. Clearly we seek a comma square $[T] >_{[T]} [T]$,

$$
\begin{array}{ccc}\n\text{Hom}[T] & \xrightarrow{\text{SRC}} & [T] \\
\text{Tr}_R \downarrow & \Downarrow & \downarrow_{\text{Id}} \\
[T] & \xrightarrow{\text{Id}} & [T]\n\end{array}
$$

Alternatively, $\text{nom}[T]$ can be expressed as the exponential $|T|$ where $\mathfrak d$ is the Sierpinski locale (whose points are the subsets of 1).

We can now make $\text{Hom}(D) \rightarrow D$ into a topical category. Using the comma object property of Hom(D), ID : $D \to \text{Hom}(D)$ corresponds to the identity 2-cell on Id_D. For composition COMP, let $\text{Hom}_2(D)$ be the pullback

$$
\begin{array}{ccc}\n\text{Hom}_2(D) & \longrightarrow & \text{Hom}(D) \\
\downarrow & \cong & \downarrow_{\text{TAR}} \\
\text{Hom}(D) & \xrightarrow{\longrightarrow} & D\n\end{array}
$$

Then we have

$$
\begin{array}{ccc}\n\text{Hom}_2(D) & \longrightarrow & \text{Hom}(D) \\
\downarrow & \cong & \text{tar } \downarrow \Leftarrow \downarrow_{\text{SRC}} \\
\text{Hom}(D) & \downarrow & D \\
\end{array}
$$

and hence $\text{COMP}: \text{Hom}_2(D) \to \text{Hom}(D)$. By definition, ID and COMP interact correctly with SRC and TAR, while the unit laws and associativity follow from the corresponding properties of 2-cells. We call this topical category the intrinsic category on D.

The topical categories that we shall use to "topologize" categorical domain theory are actually not intrinsic categories $-\text{they}$ are examples of the display categories that we shall introduce in the next section. However, wherever you have a topos you have an intrinsic category, and it turns out that some of those associated with the display categories for domains have particular domain-theoretic signicance: one, for instance, corresponds to a category of domains with embedding-pro jection pairs for morphisms.

3.1.1. "The topos of sets is not Cartesian closed" We prove this to suggest that topical CCC's are less common than you might expect. Of course, the statement must be understood rather carefully. "The topos of sets" means the topos *classifying* sets, i.e. [set] (usually known as the object classifier). This has an intrinsic categorical structure topically: its morphism topos is $Hom[set] = [fn]$, classifying two sets and a function between them. It is this topical category that is not Cartesian closed, i.e. it cannot be extended with the (essentially algebraic, and hence topically meaningful) structure of a Cartesian closed category.

The basic idea is that if [set] were a topical CCC, then exponentiation would have to be covariant in both arguments, and this is impossible.

Suppose we are given a topical CCC C , with toposes C_0 and C_1 classifying objects and morphisms, and various maps including an exponential $\mathsf{EAF}:\mathsf{C}_0^-\to\mathsf{C}_0.$ If we take global points, then we get classes pt C_0 and pt C_1 of objects and morphisms, with various functions making an ordinary (though large) CCC pt C . This includes p_1 \triangleright \triangle \triangleright \triangleright category structure of pt C. Of course, with respect to the morphisms in pt C_1 , pt EXP is contravariant in the first argument and covariant in the second. On the other hand, pt C_0 is not just a class $-$ it is a category in its own right, and with respect to the morphisms there, pt EXP is covariant in both arguments.

Now consider the case of the intrinsic topical category on [set], and suppose that it is Cartesian closed. The global points give the category \mathbf{Set} , and $\mathrm{EXP}(X, Y)$ is ordinary exponentiation Y . But pt C_0 , i.e. pt set, is also **Set**, so we have a covariant functor EAP : Set \rightarrow Set such that $\text{EAP}(X, Y) \cong Y$ Now consider (!, Id): $(\varnothing, \varnothing) \rightarrow (1, \varnothing)$ in Set \mathcal{L} EXP(!, Id) is a function from $\psi^* \equiv 1$ to $\psi^* \equiv \psi$, which is impossible.

It is also instructive, under the assumption that [set] is intrinsically a topical CCC, to consider the GU homomorphism \mathcal{S} EAP : \mathcal{S} [set] \rightarrow \mathcal{S} [set]² . This is defined by a single object of \mathcal{S} iset], and one can show that it would have to be Y – where Λ and Y are the two generic sets in $\mathcal{S}[\text{set}]^*$. But one can also calculate that Y^{**} is isomorphic to

 Y – essentially because the only functions that can be defined from one generic set to another are the constant functions. The assumption that [set] is intrinsically a topical CCC implies that this exponentiation is generic, and hence that in any geometric universe we have $Y^X \cong Y$ for all objects X and Y – an obvious nonsense.

I do not know of any topos other than 1 that is intrinsically Cartesian closed in this sense.

3.2. "Display" categories

We follow with another family of examples of topical categories, which we shall call "display categories". Hyland and Pitts (1989) use pullback-stable classes of morphisms to model dependent types, and we shall use this idea in **Top** in the case where the class is generated by a single "classifying" morphism p of which every other morphism in the class is a pullback. The paradigmatic example is the way a subob ject classical classical classical classical c classifies monics in an elementary topos - monics are pullbacks of it. Similarly, we treat p as classifying the pullbacks of it.

The prime example in toposes is the étale classifier, the forgetful map from [set][elt] (classifying sets with distinguished elements, i.e. pointed sets) to [set]: a geometric morphism $f: D_1 \to D_2$ is étale (otherwise known as a local homeomorphism) iff it is a pullback

$$
\begin{array}{ccc}\nD_1 & \longrightarrow & [\text{set}][\text{elt}] \\
f \downarrow & & \downarrow_p \\
D_2 & \longrightarrow & [\text{set}]\n\end{array}
$$

By definition of the object classifier [set], h corresponds to an object X of $SD₂$, and then SD_1 is equivalent to the slice geometric universe SD_2/X .

Now for the subobject classifier, the morphism along the bottom is *uniquely* determined by the monic. For the étale maps, h is defined uniquely by f only up to isomorphism, and in fact there are examples of display categories where even that uniqueness up to isomorphism doesn't hold. Hence what p classifies is really pullbacks of it equipped with specified pullback squares and so the notion of "classifying" is somewhat weaker that with the subobject classifier; but the comparison is still useful.

Let us call such pullbacks p-displays. If $f: D_1 \to D_2$ (equipped with a pullback square) is a p-display, let us call D_1 a p-topos over D_2 . Given a topos D, consider p-Top $/D$, the full subcategory of Top/D whose objects are p-toposes. Our interest lies in devising p to capture various notions of topos ${\bf -}$ mostly locales, actually ${\bf -}$ over (arbitrary) D as $p\text{-Top}/D$. We have already seen how to capture discrete spaces (étale maps) using $p : [set][elt] \rightarrow [set],$ and then p -Top $/D \simeq SD$. A second main example is that of algebraic dcpos: if we take p to be the forgetful map (forgets the ideal) from [poset][ideal] to [poset], then it's the ideal completion of the generic poset, and we have already argued that it classies algebraic dcpos. (Note that there is a discordance here with the way Hyland and Pitts (1989) use the word "algebraic". For them, an algebraic topos D is one that classifies an essentially algebraic theory: its geometric universe SD is a presheaf category $\mathbf{Set}^{\mathbf{C}^{\mathsf{T}}}$ for some finite limit category C, and a localic algebraic topos is one for which C is a poset $-$ hence a meet semilattice. Our algebraic dcpos are locales D (localic toposes) for which SD is $Set^{C^{r}}$ for an *arbitrary* poset C, and it would indeed be natural for us to define a topos to be algebraic if SD is Set^{CT} for an arbitrary category.) Other kinds of locales that can be captured (sometimes in several constructively inequivalent ways) include continuous dcpos, Scott domains, strongly algebraic (SFP) domains, Stone locales, spectral locales, etc., etc. $-$ we shall discuss some of these more fully in a later section. The main body of the paper will be concerned with strongly algebraic domains because of their computer science interest.

Let us fix notation for a general scheme so far: we have a theory IS of *information* systems (e.g. the theory of posets), a theory $IS + pt$ of points of information systems (e.g. ideals of posets), and a map $p : [IS][pt] \rightarrow [IS]$. Pullbacks of this will be called *domains* (though predomains would often be a more conventional term, because we don't usually assume bottom points). We shall assume that p is exponentiable, and therefore have $[AM] = (P_s p \Rightarrow_{[IS]^2} P_t p)$, where P_s and P_t are the two projections from $[Is]$ to $[Is]$ (cf. Theorem 2.4.4).

 $[AM]$ is a topos over $[iS]$, so we certainly have two geometric morphisms SNC and TAR from [AM] to [IS] (corresponding to P_s and P_t). Let us show that these form the source and target maps of a topical category. Remember that the characterization of $[AM]$ as an exponential over $|I5|$ enables us to define maps from any D into $[AM]$ as pairs (r_s, r_t) of maps from D to [15] together with a map from P_s p to P_t p over D.

The identity map ID : $[IS] \rightarrow [AM]$ is given by the pair (Id, Id) of maps from [IS] to itself, together with the identity map from Id p to Id p .

Let $[AM_2]$ be the theory of two composable approximable mappings, in other words the pullback

$$
\begin{array}{ccc}\n[AM_2] & \longrightarrow & [AM] \\
\downarrow & \cong & \downarrow_{\text{TAR}} \\
[AM] & \underset{\text{SRC}}{\longrightarrow} & [IS]\n\end{array}
$$

We have three maps from $[AM_2]$ to $[IS]$ – or, more carefully, four maps with an isomorphism between the middle two. Accordingly, we get four domains over [AM2]. The two maps to [AM] give maps over $\text{[AM}_2\text{]}$ between the first two domains and between the last two, and the isomorphism gives an equivalence between the middle two. Composing gives a map between the first and last, corresponding to a map from $[M_2]$ to $[AM]$. This is COMP, for composition.

By definition, ID and COMP interact correctly with SRC and TAR. The unit laws and associativity follow essentially from the corresponding properties of maps, though we have somewhat glossed over the 2-categorical aspects here. We shall call the resulting topical category the *display category* obtained from p.

Example 3.2.1. When p is the étale classifier, then its display category is equivalent to the intrinsic category on [set]. This is because maps between discrete locales are equivalent to functions (homomorphisms) between the corresponding sets.

Our main aim in this paper is to show how a specic class of domains, namely the strongly algebraic (or SFP) domains, can be put into a topical setting to exemplify an

account of categorical domain theory that in many respects works much more smoothly than the usual one. The strongly algebraic domains are chosen for exactly the usual reason, namely that the (topical) category of them is Cartesian closed and supports domain theoretic constructions including the Plotkin power domain.

3.2.1. Capturing extra structure on the display category Categories of domains are generally Cartesian (finite products), and a few are Cartesian closed. If bottoms are not required, then the categories are generally also coCartesian. All these kinds of extra structure can be expressed using essentially algebraic (nite limit) theories, and so are meaningful for internal categories in any category with nite limits. Unfortunately, the category of toposes is actually a 2-category, and pullback squares commute only up to isomorphism. Because of these complications we shall not here attempt to work with a proper 2-categorical definition of "internal category" (Hyland and Moerdijk unpublished).

Instead, when we come to investigate a particular p in Section 4 we shall show how its properties lead to $p\text{-Top}/B$ inheriting structure from Top/B , so that constructions on p-toposes will agree with those pertaining to more general toposes. For instance, p -**Top**/B can inherit terminal objects from Top/B as follows. Suppose there is a global point TERM of [IS] (i.e. TERM : $1 \rightarrow$ [IS]) that looks as though it ought to be the terminal object in an internal category sense. For any topos B we get a corresponding p topos over B , namely (i; TERM) [IS][pt], and what we do is to show that this is terminal in Top/B. Similarly, p-Top/B can inherit binary products from Top/B. We give a map PROD : $[IS]^2 \rightarrow [IS]$, and show that for any two p-toposes D_1 and D_2 over B, corresponding to $f : B \to |\mathbf{I}S|$, the pullback $(f : \mathbf{P}\mathbf{R}\cup\mathbf{D})$ [is equivalent to the product D1 - D2 - D2 - D2 p7

3.2.2. Examples We can now extend the negative result of Section 3.1.1 to cover more $particular sets - specifically, finite sets and decidable sets. These give two geometric$ theories extending that of sets:

FinSet is presented with a constant $\top : \mathcal{F}X$ and an axiom $\vdash_{x:X} x \in \top$

 \mathbf{E} is presented with a binary relation 6 \mathbf{X} - \mathbf{X} complement of equality:

$$
\begin{aligned} \mathbf{true} \vdash_{x,y:X} x = y \lor x \neq y \\ x \neq x \vdash_{x:X} \mathbf{false} \end{aligned}
$$

These are localic over [set], because they are presented without any new sorts. They are not subtoposes of [set], even though non-constructively one might think of finiteness or decidability as particular properties of a set X (i.e. just extra axioms). Actually, they represent extra *structure* on X, and this shows up in the homomorphisms. Because \top or \neq must be preserved, homomorphisms of finite or decidable sets must be, respectively, onto or 1-1.

It is normal to presume that the category Set of sets is Cartesian closed, but we have shown that the intrinsic topical category for [set] is not. We might therefore ask whether perhaps $[DecSet]$ is $-$ maybe in [set] we omitted too much of the constructive structure.

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The answer is No, but let us first take care to phrase the question properly. We are not interested in the intrinsic topical category on [DecSet], because that corresponds to the category of sets with 1-1 functions and that is certainly not Cartesian closed. (It does not even have a terminal object, nor binary products.) To get a topical category whose morphisms correspond to all functions between decidable sets, we take the display category arising from the étale classifier when pulled back to [DecSet].

Let us now show that this display category is not Cartesian closed. Suppose that it is, with exponentiation map $EXP : [DecSet]^2 \rightarrow [DecSet]$. Taking global points just as in Section 3.1.1 we find that pt EAP is a covariant functor from $\texttt{Set}_{\text{mon}}$ to $\texttt{Set}_{\text{mon}}$, where Set_{mon} is the category of sets with monos, and that, on objects, it takes (X, Y) to Y^* . The argument is now the same as before, because the functions ! and Id used there are both 1-1.

Now let us turn to the finite sets. Classically, the category $\mathbf{Set}_{\text{fin}}$ of finite sets is Cartesian closed. Again, we pull back the étale classifier to [FinSet] and consider the display category that arises. Assuming that it is Cartesian closed topically, we find that pt EXP is a covariant functor from \texttt{Set}_{fo} to $\texttt{Set}_{\text{fo}},$ where \texttt{Set}_{fo} is the category of finite sets with onto functions, and that, on objects, it takes (X, Y) to Y^{\pm} . Now let Y be any non-empty finite set. $\colon Y \to 1$ is onto, and so is Id Y, so there is a function pt EXP(!, Id) : $Y^Y \to Y^1 \cong Y$. Let $h_Y \in Y$ be the image of Id_Y under this function. We show that h_Y is invariant under all permutations of Y, for let $\sigma: Y \to Y$ be one. We have a diagram (*)

$$
\begin{array}{ccccccc}\n1 & \longrightarrow & Y^Y & & & \xrightarrow{\text{pt } \operatorname{EXP}(\mathbf{I},\mathrm{Id})} & Y^1 & & \xrightarrow{\cong} & Y \\
\parallel & & \downarrow_{\text{pt } \operatorname{EXP}(\sigma,\sigma)} & & & \downarrow_{\text{pt } \operatorname{EXP}(\mathrm{Id},\sigma)} & & \downarrow_{\sigma} \\
1 & \longrightarrow & Y^Y & & & \xrightarrow{\text{pt } \operatorname{EXP}(\mathbf{I},\mathrm{Id})} & Y^1 & & \xrightarrow{\cong} & Y \\
\end{array}
$$

The two unlabelled morphisms from I to Y T both select the identity function.

We wish to show that this diagram commutes, for this will show that $\sigma(h_Y) = h_Y$ are desired. The middle square is obvious, because both arms come to pt $EXP(!, \sigma)$. For the others we need to investigate the vertical maps. We prove a Lemma that may well generalize to cover other topical display categories.

Lemma 3.2.2. Assuming that the topical display category on [FinSet] is Cartesian closed, let there be a diagram as follows. The objects are finite sets, n, n , κ and κ are all surjective, and the two outer squares commute.

$$
\begin{array}{ccccccc}\nX_1 & \stackrel{f_1}{\longrightarrow} & X_1' & \stackrel{\phi}{\longrightarrow} & Y_1 & \stackrel{g_1}{\longrightarrow} & Y_1' \\
h \downarrow & & & h' \downarrow & & & k \downarrow & & k' \downarrow \\
X_2 & \stackrel{\rightarrow}{\longrightarrow} & X_2' & & & \text{pt } \exp(h',k)(\phi) & & & & g_2 & & Y_2'\n\end{array}
$$

Then the middle square commutes, and the bottom composite edge of the overall rectangle is equal to pt $\mathbb{E} \Lambda \Gamma(n, \kappa) \setminus f_1; \varphi; g_1$.

Proof. We prove the second part first. Consider the exponential on functions, contravariant in the first argument and covariant in the second. This exists simply by virtue of the internal CCC structure. If C_1 is the topos classifying two finite sets and a function

between them, then this exponential is a map MEAP $:C_{\bar{1}} \to C_1$. This is functorial with respect to homomorphisms between points, and a homomorphism between points of C_1^2 is just a pair of commutative squares like the outer two in the given diagram, and so we obtain a commutative square (a homomorphism between points of C_1) like this:

$$
\begin{array}{ccc}&&Y_1^{X_1'}&\xrightarrow{g_1^{f_1}}&Y_1'^{X_1}\\ \text{pt}\,\text{EXP}(h',k)&\downarrow&&\downarrow\text{pt}\,\text{EXP}(h,k')\\ &&Y_2^{X_2'}&\xrightarrow[g_2^{f_2}&&Y_2'^{X_2}\\ \end{array}
$$

Applying the two arms of this to an element ϕ of $Y_1^{\Lambda_1}$ gives our result.

Commutativity of the middle square follows by taking $\Lambda_1 = \Lambda_2 = \Lambda_1, J_1 = h = \text{i} \alpha_{X_1},$ and $j_2 = n$, and $Y_1 = Y_2 = Y_2, \, \kappa \, = g_2 = \text{Id}Y_2$ and $g_1 = \kappa$. Then at the bottom we have μ ; pt EXP(μ , κ)(φ); Id = pt EXP(Id, Id)(φ ; κ) = φ ; κ .

Let us apply the lemma in the case when all the objects are Y and $h' = k = \sigma$. We see that pt $\text{EAP}(\sigma, \sigma)(10) = \sigma^{-1}(10; \sigma = 10, 10)$ other words the left-hand square in (*) commutes. Now if we take $X_1 = X_2 = 1$ then we see that $\mathsf{pt} \text{ Ext}(\mathfrak{u}, \sigma)(\psi) = \psi; \sigma$ for all $\phi: 1 \rightarrow Y$, and this translates into commutativity of the right-hand square.

Finally, the contradiction follows by taking $Y = 2$ and σ to be the swap permutation, which has no fixpoints.

For a more positive example, we can now describe a display category that is Cartesian α closed $-$ that of finite decidable sets. (The argument is already present to some extent in Acuña-Ortega and Linton (1979).) Its display map $p : [FinDecSet][elt] \rightarrow [FinDecSet]$ is the pullback along [FinDecSet] \rightarrow [set] of the étale classifier. (Note that the intrinsic category on [FinDecSet] is not Cartesian closed at all. Indeed, it is a topical groupoid, for a homomorphism between finite decidable sets must be 1-1 and onto, and hence an isomorphism.) The main point of difficulty lies in defining the exponentials. If X and Y are finite decidable, then $[X \Rightarrow Y]$ can be defined geometrically as

$$
\{f \in \mathcal{F}(X \times Y) | \newline \forall x \in X. \exists y \in Y. (x, y) \in f \land \forall (x_1, y_1), (x_2, y_2) \in f. (x_1 \neq x_2 \lor y_1 = y_2) \}
$$

Using Theorem 2.1.6 and Proposition 2.1.9, this is finite decidable.

4. Strongly algebraic domains

The notion of strongly algebraic (or SFP) domain is due to Plotkin (1976), who gave a variety of mathematical formulations. There are various flavours, and for our present purposes we shall assume neither a bottom point, nor second countability (i.e. the set KD of compact points need not be countable).

Recall the classical definition: an algebraic dcpo D is a *strongly algebraic domain* iff

1 Every finite subset S of KD has a finite, complete set $MUB(S)$ of minimal upper bounds in KD . Here "complete" means that every upper bound of S is greater than one of those in $MUB(S)$.

2 Given $S \subseteq_{\text{fin}} K D$, define $\text{MUB}_0(S) = S$, and

$$
\text{MUB}_{i+1}(S) = \bigcup \{ \text{MUB}(U) : U \subseteq \text{MUB}_i(S) \}
$$

$$
\text{MUB}_{\omega}(S) = \bigcup_i \text{MUB}_i(S)
$$

We require that $\text{MUB}_{\omega}(S)$ (the *MUB-closure* of S) should be be finite for every S.

We shall describe a geometric theory whose models are "strongly algebraic information systems" $-$ those posets satisfying the conditions for KD given above. However, there are certain issues raised by the constructive constraints.

First, is the order decidable? We shall discuss this question here later (Section 4.6) in more detail, but let us say straight away that we shall not assume decidability. In fact, taking the order decidable or not gives two distinct constructive theories of strongly algebraic information systems. The undecidable version that we present here $-\text{ which}$ is the harder one when it comes to describing domain constructors $-$ is essentially that given in Abramsky (1991).

Second, the requirement of *minimality* for the bounds in $MUB(S)$ is problematic if the order is undecidable. Classically, if S is a finite subset of a poset then we can discard the non-minimal elements to obtain a subset $\text{Min}(S)$ comprising the minimal elements of S, but constructively this is impossible without decidability of \subseteq . If it were possible, then homomorphisms between posets $-$ i.e. monotone functions $-$ would have to preserve Min. This is not so, as can be seen by considering the posets $2 = \{0, 1\}$, with the discrete ordering, and $I = \{\perp, \top\}$, with $\perp \sqsubseteq \top$. There is a monotone function $f : 2 \to I$ that maps 0 and 1 to \perp and \perp respectively. Min $\{0, 1\} = \{0, 1\}$, but Min $\{\perp, \perp\} = \{\perp\}$, which is not the image of $\{0,1\}$ under f. When \sqsubseteq is decidable, then homomorphisms must also preserve $\not\sqsubseteq$ and hence are order embeddings. These do preserve Min, and indeed Min(S) can be expressed geometrically as $\{t \in S \mid \forall s \in S. (s \not\sqsubseteq t \vee s = t)\}\.$ We shall drop the insistence on minimality and simply require, for each finite set S , the existence of a finite set T that is a complete set of upper bounds of S (and we write $CUB(S,T)$ to express this).

Finite MUB-closures are similar: instead of describing $MUB_{\omega}(S)$ explicitly and requiring it to be finite, we shall postulate the existence of some finite set $T \supset S$ such that every finite subset of T has a complete set of upper bounds contained in T .

We express this as a geometric theory as follows:

Definition 4.0.3. The theory IS of *(strongly algebraic) information systems* is presented as follows:

- 1 a single sort, X (whose elements are commonly called *tokens*)
- 2 a binary predicate ^v X X
- 3 axioms to make \sqsubseteq a partial order:
	- (a) $\vdash_{t:X} t \sqsubset t$
	- (b) $s \sqsubseteq t \wedge t \sqsubseteq u \vdash_{s,t,u:X} s \sqsubseteq u$
	- (c) $s \sqsubset t \wedge t \sqsubset s \vdash_{s t : X} s = t$
- $\mathbf{f} = \mathbf{f} \cdot \mathbf{f} + \mathbf$

- 5 axioms to say that if $CUB(S, T)$ holds then T is a complete set of upper bounds for S :
	- (a) CUB $(S, T) \vdash_{S,T:FX} \forall s \in S. \forall t \in T. s \sqsubset t$
	- (b) CUB $(S, T) \wedge \forall s \in S$: $s \sqsubseteq u \vdash_{S,T; \mathcal{F}X, u:X} \exists t \in T$. $t \sqsubseteq u$
- 6 an axiom to say that every finite set of tokens has a finite complete set of upper bounds:

$$
\vdash_{S:\mathcal{F}X} \exists T : \mathcal{F}X. \text{CUB}(S,T)
$$

7 an axiom to ensure that if T is a finite complete set of upper bounds for S , then $CUB(S, T)$ holds:

$$
\forall s \in S. \forall t \in T. s \sqsubseteq t \land \text{CUB}(S, T') \land \forall t' \in T'. \exists t \in T. t \sqsubseteq t' \\
 \vdash_{S,T,T':\mathcal{F}X} \text{CUB}(S,T)
$$

8 an axiom to say that every finite set of tokens has a finite CUB-closure

 $\vdash_{S:FX} \exists T : \mathcal{F}X.(S \subseteq T \wedge \mathrm{CUBcl}(T))$

where $\text{CUBcl}(T) \equiv_{\text{def}} \forall U \subseteq_{\text{fin}} T . \exists V \subseteq_{\text{fin}} T . \text{CUB}(U, V)$

 $Notes -$

- 1 Axiom (6) is a consequence of (8) and hence superfluous. However, we make it explicit in order to point out that $(1)-(7)$ axiomatize the *spectral algebraic* or $\frac{2}{3}$ SFP information systems.
- 2 We have that

$$
CUB(S, T) \Leftrightarrow \forall s \in S. \forall t \in T. s \sqsubset t \land \forall u. ((\forall s \in S. s \sqsubset u) \rightarrow \exists t \in T. t \sqsubset u)
$$

The \Rightarrow direction is just a rewriting of axioms (5). For \Leftarrow , choose T such that CUD(S, I). If $t \in I$, then $\forall s \in S$ s $\sqsubset t$ and so $\exists t \in I$ is $\sqsubset t$; we can now use (7).

- 3 It follows from Note 2 that the axioms for CUB make it uniquely determined by \Box . Hence the map $[IS] \rightarrow [poset]$ is a monomorphism of toposes, though it is not an inclusion. (If it were, i.e. if [IS] were a subtopos of [poset], then its structure would have to be inherited from [poset] and in particular the homomorphisms of information systems would just be the monotone functions between posets. But we shall see later that preservation of CUB makes them more restricted.)
- 4 Classically, this new definition is equivalent to the old one: a poset (X, \square) is equivalent to the set of compact points of a strongly algebraic domain iff it can be equipped with a predicate CUB making it a model for IS. For the \Rightarrow direction we can define $\text{CUB}(S, T)$ iff T is a complete set of upper bounds of S, and for \Leftarrow , suppose $S \subseteq_{\text{fin}} X$ and $\text{CUB}(S, T)$. By taking the minimal elements of T, we get a finite complete set of minimal upper bounds of S. Let $U \supseteq S$ be finite and CUB-closed. The chain $(MUB_i(S))$ can be constructed in U, and so $MUB_{\omega}(S) \subset U$ is finite.
- 5 In practice, we don't need to describe CUB fully. For suppose X, \sqsubseteq and CUB₀ satisfy axioms (1) - (6) in the Definition for X , \sqsubseteq and CUB. Then we can make a unique

spectral algebraic information system using X and \subseteq by defining CUB(S, T) as the

$$
\forall s \in S. \forall t \in T. s \sqsubseteq t \land \exists T' : \mathcal{F}X. (\mathbf{CUB}_0(S, T') \land \forall t' \in T'. \exists t \in T. t \sqsubseteq t')
$$

- 6 A discrete poset (i.e. a set X) can be equipped with the structure of a strongly algebraic information system iff it is finite and decidable. If X is equipped with CUB, then for some finite S we have CUB(\emptyset , S), from which we see that $X = S$ is finite; and $s \neq t$ iff CUB({s, t}, \emptyset). Conversely, if X is finite decidable then CUB(S, T) iff $S = \emptyset$ and $T = X$, or $S = \{s\} = T$ for some s, or there are $s \neq t$ in S and $T = \emptyset$.
- 7 Vickers (1998) shows that IS is equivalent to the theory of at presheaves over a c category C whose objects are finite cardinals equipped with finite partial orders and whose morphisms are adjunctions (the reason for that choice of morphisms will become more apparent in the light of Proposition 4.0.6). By Diaconescu's theorem, this shows that that $\mathcal{S}[\mathbf{I}\mathbf{S}]$ is equivalent to the functor category \mathbf{Set}^+ . It is also shown that this result is the geometric analogue of Plotkin's alternative characterization of strongly algebraic domains as "SFP" (Sequence of Finite Posets). Corresponding results hold for variations on IS that we discuss later, including decidable information systems (Section 4.6), and information systems with bottom, with or without termination predicate (Section 5).

Definition 4.0.4. A *strongly algebraic domain* is the ideal completion of a strongly algebraic information system. More precisely, there is an obvious map from [IS] to [poset], and the pullback along this of the algebraic dcpo classier is the strongly algebraic classifier. We shall usually write it as $p : [IS][pt] \rightarrow [IS]$. A strongly algebraic domain (over a given topos) is a pullback of the classifier.

We have already mentioned that our domains without bottom might more usually be called predomains. However, a more subtle connotation of "predomain" is "something whose lift is a domain" so that one can move between domains and predomains by adding or removing bottom. This is not possible for us. For instance, all flat domains (lifted sets) are strongly algebraic, but by note (6) above the unlifted sets are not, except when finite decidable.

From the general theory of algebraic dcpos, we know that maps between strongly algebraic domains are given by approximable mappings. Hence we get a theory AM of strongly algebraic approximable mappings, i.e. those for which the source and target posets are both strongly algebraic information systems.

Besides the continuous maps between domains, it is interesting also to consider the homomorphisms between information systems, defined in the standard way for models of a geometric theory.

Definition 4.0.5. Let X and Y be two strongly algebraic (or, indeed, spectral algebraic) information systems. A homomorphism from X to Y is a monotone function $f: X \to Y$ that preserves CUB:

$$
CUB(S, T) \Rightarrow CUB(f(S), f(T))
$$

Proposition 4.0.6. Let X and Y be strongly algebraic (or spectral algebraic) information systems. Then there is a bijection between $=$

 \longrightarrow homomorphisms from X to Y

 \longrightarrow adjunctions between Idl(X) and Idl(Y)

Proof. If $f : X \to Y$ is any monotone function, then we have an approximable mapping $\phi: X \to Y$ defined by $s \phi t$ iff $f(s) \sqsupset t$, and f can be recovered from ϕ because $f(s)$ is the greatest t such that $s\phi t$. We can also define a relation ψ from Y to X (not necessarily an approximable mapping) by $t \psi s$ iff $t \supseteq f(s)$. Then $\supseteq \psi$; $\supseteq \psi$, and ψ is right adjoint to ϕ in the sense that ϕ ; $\psi \supseteq \exists x$ and ψ ; $\phi \subseteq \exists y$. These conditions suffice to make ψ uniquely determined by φ , for two intervals $s\varphi\iota\,\to\iota\perp\iota$). But for an arbitrary approximable mapping ϕ , if it has such a right adjoint ψ then f exists: for for any $s \in X$ we can find t with $s\phi t\psi s$, and t is the greatest such that $s\phi t$ and hence unique. We take $f(s)$ to be this t.

We have thus shown a correspondence between, on the one hand, monotone functions $f: X \to Y$, and, on the other, adjoint pairs (ϕ, ψ) where ϕ is an approximable mapping from X to Y and ψ is a relation from Y to X with $\Box; \psi; \Box = \psi$. It remains to show that ψ is an approximable mapping iff f preserves CUB.

Suppose $S, T \subseteq_{fin} X$ and $CUB(S, T)$. Then $\forall x \in S.uv \$ holds iff u is an upper bound for $f(S)$. ψ is an approximable mapping iff in all such contexts we have $u\psi t$ with t an upper bound for S, i.e. $u \psi t$ with $t \in I$, i.e. $u \supset$ some element of $f(T)$, and this is exactly what is needed to show $\text{CUB}(f(S), f(T))$.

Leading on from this, one can show that, using the definitions of Johnstone (1993), the strongly algebraic classifier is both a fibration (homomorphism f gives map ψ) and an opfibration (f gives ϕ).

We shall now look at constructions on strongly algebraic domains $-$ products, coproducts, function spaces and so on. (It is worth noticing that the general techniques seen in Hyland and Pitts (1989) indicate how to go beyond these domain constructions to the construction of terms for maps between domains $-$ as also appear in Abramsky (1991) .) For each of these constructions we show how to construct a new information system out of old ones, and there are usually two issues. First, does the new one have the right points? (Is the corresponding pullback of p the topos that we asked for in Section 3.2.1 and described in Section 2.2?) Second, is the constructed information system still strongly algebraic?

In fact, this work is largely indebted to that of Abramsky (1991). He gave a localic account of SFP domains (with bottom) by describing a formal language for the compact α opens that appear in various constructions $-\text{specifically},$ products, coalesced sums, lifting, functions spaces, the Plotkin power domain, and solutions of recursive domain equations. (Our treatment differs, in a way that has been suggested by Abramsky himself, in that we use the information systems $-$ the posets of compact points $-$ instead of the distributive lattices of compact opens. This generally simplifies the presentation $-$ though perhaps not for the function spaces $-$ but the difference is not a deep one.)

Part of Abramsky's method relies on certain predicates on the terms that represent compact opens: binary predicates \leq and $=$, and unary predicates **C** and **T** (**C**(*a*) means

that a is a coprime compact open, corresponding in our setting to a token; $\mathbf{T}(a)$ means that $a \neq \text{true}$. Because of the presence of the recursive solutions to domain equations, the definitions of these predicates are also recursive and so it is essential that the predicates occur positively in the denitions. For instance, one cannot ensure merely by definitional flat that if $\neg(a = \text{true})$ then $\mathbf{T}(a)$, because the recursive nature means that one only gradually discovers which a 's are equal to **true**. **T** must be defined by positive means, after which it is possible to prove that $\mathbf{T}(a) \Leftrightarrow a \neq \mathbf{true}$.

Because of this, the requirements of positivity and constructivity called for by the use of geometric logic were also called for on quite immediate computational grounds in Abramsky's work, and so essentially the work of constructivizing has already been done by him. But one can also look at this in reverse: the use of geometric logic implied by the topologization programme automatically imposes strong constructive constraints that turn out to be necessary in syntactic computation. Compare this with the lack of constraints imposed by classical logic in Vickers (1989): the apparently simpler treatment there sometimes uses arguments that are constructively useless in Abramsky's formal system, a good example being the account of strongly algebraic function spaces. However, there is a much deeper point. The word "constructive" is often used to mean just "valid" in any elementary topos", but impredicative reasoning in such constructivism can also evade the algorithmic content that Abramsky needs. It seems that it is the stronger geometric constraints that force us to consider the algorithms.

A more mundane difference, though a significant one, is Abramsky's restriction to local domains (i.e. with bottom). This makes it necessary to have a different treatment of sums (because our coproducts are not local), and to construct amalgamated sums one requires a predicate to describe the negative information of when a token is not bottom $-$ this appears as Abramsky's "termination" predicate \bf{T} mentioned above. This issue is discussed further in Section 5.

4.0.3. Pre-information systems In Definition 4.0.3 we defined our information systems to be partial orders. It is actually often more convenient to work with preorders. For instance, for the Plotkin powerdomain $P D$, the tokens can then be considered to be finite sets of tokens of D, under the Egli-Milner ordering, a preorder. However, certain technical simplications come from the partial ordering assumption. We shall now show that in fact we can get the best of both worlds by taking the poset reflection of a preorder. The technical point is that the axiomatization of CUB is so closely constrained by the order that it too respects the poset reflection.

Definition 4.0.7. The theory of (strongly algebraic) pre-information systems is defined exactly as in Definition $4.0.3$, but with the order allowed to be a preorder: Axiom $3c$ (antisymmetry) is omitted.

Proposition 4.0.8. Let $(X_0, \subseteq, \text{CUB}_0)$ be a pre-information system, and let (X, \subseteq) be the poset reflection of (X_0, \subseteq) with quotient function $f: X_0 \to X$. Define

 $CUB(S, T) \equiv_{def} \exists S_0, T_0 : \mathcal{F}X_0. (S = f(S_0) \wedge T = f(T_0) \wedge CUB_0(S_0, T_0))$

Then $(X, \subseteq, \text{CUB})$ is an information system.

Proof. Straightforward. Note that if $S = f(S_0) \wedge T = f(T_0)$, then the intuitionistic

$$
\forall s \in S. \forall t \in T. s \sqsubseteq t \land \forall u. ((\forall s \in S. s \sqsubseteq u) \rightarrow \exists t \in T. t \sqsubseteq u)
$$

is equivalent to the corresponding one in X_0 for S_0 and T_0 , which is equivalent to $\text{CUB}_0(S_0, T_0)$.

4.1. Products

Given two information systems, X_1 and X_2 , their product is defined as follows: the poset is the product order, r is the product order, (s1; s2) r (t1; t2) in the s2 r and s2 v t2.

We haven't defined CUB yet, but already it is clear that if we can, then this is indeed the product: for an ideal I of I \mathbf{r}_1 , \mathbf{r}_2 is equivalent to a pair of ideals, one from each X_i : $I_1 = \{x_1 \mid \exists x_2 \ldots (x_1, x_2) \in I\}$ and I_2 is similar. Of course, one should check that the argument is geometric.

Next, we show that the new information system is strongly algebraic. CUB is defined as in note 5 after Definition 4.0.3 from $\text{CUB}_0(S,T)$, defined as

9T1 : FX1; T2 : FX2:(CUB(p1(S); T1) ^ CUB(p2(S); T2) ^ ^T ⁼ T1 - T2)

where p_i is the *i*th projection. The basic reasoning is that (s_1, s_2) is an upper bound for S iff each s_i is an upper bound for $p_i(S)$. If M_i is CUB-closed containing $p_i(S)$, then $\mathcal{L} = \mathcal{L}$ is contained containing \mathcal{L} .

The terminal domain is the nullary analogue of this: the poset is $1 = \{*\}$, and $CUB(S, T)$ holds iff $T = \{*\}.$

4.2. Coproducts

Given two information systems X_1 and X_2 , their sum is defined as follows. The poset is the coproduct (disjoint union) $X = X_1 + X_2$ with the sum order: $s \subseteq t$ iff s and t are in the same component X_i , and $s \sqsubseteq t$ in X_i .

To show that this sum gives a coproduct of toposes, we must show that ideals of X are in 1-1 correspondence with points of the coproduct (see Section 2.2). If I is an ideal of X, then we have a complementary pair of propositions $P \equiv \exists x : X_1.I(x)$ and $\neg P \equiv \exists x : X_2 \cdot I(x)$. Writing $I_i = I \cap X_i$, we get that I_1 or I_2 is an ideal of X_1 or X_2 according as P or $\neg P$, so if P then I_1 else I_2 is a point of Idl(X_1) + Idl(X_2). Conversely, given if P then I_1 else I_2 , then $I = I_1 + I_2$ is an ideal of X.

Noting that $\mathcal{F}(X_1 \pm X_2) = \mathcal{F}(X_1 \wedge \mathcal{F}(X_2))$ (the free algebra functor \mathcal{F}). Set \rightarrow Semiliattice preserves all colimits, and for semilattices Cartesian product is a biproduct), we can de fine

$$
CUB((S_1, S_2), (T_1, T_2)) \equiv_{\text{def}} CUB(S_1, T_1) \wedge CUB(S_2, T_2)
$$

and if M_i is CUB-closed containing S_i : $\mathcal{F}X_i$ then (M_1, M_2) is CUB-closed containing (S_1, S_2) .

The initial domain is the nullary analogue: the poset is \emptyset , and its unique finite subset ; is CUB-closed.

Some remarks on the coalesced sum used by Abramsky (1991) can be found in Section 5.

4.3. Lifting

If X is an information system, then its lift X_{\perp} is the poset $\{\perp\} + X$ ordered by $s \sqsubseteq t$ iff $s = \perp$ or $s \sqsubseteq t$ in X.

If $S : \mathcal{F}X_{\perp}$, then we can write S uniquely as $S_1 + S_2$ where $S_1 : \mathcal{F}{\perp}$ and $S_2 : \mathcal{F}X$. Then we define $\mathrm{CUB}_0(S,T)$ as

$$
\exists T': \mathcal{F}X. (\text{CUB}(S_2, T') \land T = \{\perp \mid S_2 = \emptyset\} + \{t \in T' \mid S_2 \neq \emptyset\})
$$

If M is CUB-closed containing S_2 , then $\{\perp\} + M$ is CUB-closed containing S.

The proof that the points are right is somewhat similar to that for coproducts. If I is an ideal of X_{\perp} , then by taking $P = \{ * \in 1 \mid \exists x : X.I(x) \}$ we get a P-indexed family of ideals of X , where P is a subset of 1.

4.4. Exponentials (function spaces)

Despite the expositional differences, the mathematical substance of this section is very much based on that of Abramsky (1991) , starting from his Definition 3.4.1. We shall see how the geometric constraints automatically impose the constructivity that Abramsky required.

Let X_s and X_t be two information systems. We wish to define another information system $[X_s \Rightarrow X_t]$ whose points are the approximable mappings from X_s to X_t , and the compact points will be the approximable mappings f that are determined by a finite and the compact of the compact \mathcal{S} . In the compact \mathcal{S} of the compact of the compact operation \mathcal{S} ogy, any U corresponds to a basic open, the corresponds to a basic open, the subset of the su $\{f \mid f(\tau x) \subseteq y\}$ for $(x, y) \in U$.) Abramsky identified conditions on U (our "fully summarizing") for there to be a least approximable mapping containing it.

 \sim 1.4.1.1. We shall write product ps and pt in the product product product product product product \sim

- \pm . Suppose V ; W \pm in that W is a summary of V is a summary of \pm V is a summary \pm a complete set of upper bounds for $p_s(V)$ and $p_t(W)$ is a set of upper bounds (not necessarily complete) for $p_t(V)$.
- \mathbb{R}^2 \ge 2011 And \mathbb{R}^2 is functional eventy in U.S. (Note that a summarizing in U.S. (Note that that this is a geometric property of U .)
- $\qquad \qquad \vdots \qquad \qquad \vdots$

$$
U \sqsubseteq U' \equiv_{\text{def}} \forall (u_s, u_t) \in U \exists (u'_s, u'_t) \in U'. (u_s \sqsupseteq u'_s \land u'_t \sqsupseteq u_t)
$$

4 The (pre-)information system $[X_s \Rightarrow X_t]$ has for its tokens the fully summarizing nite subsets of α , ordered by v. ordered by v. order

Let us note immediately the following lemma:

Lemma 4.4.2. Let $U, U \subseteq$ $_{\text{fin}}$ $\Lambda_s \times \Lambda_t$ with U fully summarizing.

- 1 An approximable mapping f_U can be defined by x f_U y iff $\{(x, y)\}\subseteq U$. It is the least approximable mapping containing U.
- 2 $U' \sqsubseteq U$ iff $U' \subseteq f_U$.
- $3 \pm U$ also is fully summarizing, then $U \sqsubseteq U$ in $JU' \subseteq JU$.

Proof. The only part that presents any difficulty is the "ideal" condition of approximable mappings in (1). Suppose x J_U y_i (1 \leq 1 \leq n), with $x \perp x_i$, $y_i \perp y_i$ and $(x_i, y_i) \in U$. Let $V = \{(x_i, y_i) \mid 1 \leq i \leq n\}$, and let W be a summary for it in U. Then since x is an upper bound for $p_s(V)$ we have $x \supseteq x''$ for some (x'', y'') in W, and then x f_U y'' and y'' is an upper bound for the y_i 's.

CUB (or rather, as in note 5 after Definition 4.0.3, $CUB₀$) is defined by what is in effect a description in geometric logic of Abramsky's (1991) normalization algorithm for function spaces (which normalizes expressions representing compact opens of the function space). Of course, we already have an intuitionistic formulation of CUB, but we require a geometric one. Because of the positivity of the logic, that will have the avour of attaining CUB "from below", and is where the geometric constraints force us to give algorithmic content.

 $-$ - and consider a preorder α , and α , α , α , α is a second intuition intuition α , α , α is a second

$$
\forall V \in \mathcal{V}.\exists U \in \mathcal{U}.U \sqsubseteq V
$$

$$
\land \forall U \in \mathcal{U}.\forall f \subseteq X_s \times X_t. (f \text{ an approximate mapping } \land U \subseteq f
$$

$$
\rightarrow \exists V \in \mathcal{V}.U \sqsubseteq V \subseteq f)
$$

Lemma 4.4.3. If $\mathcal{U}, \mathcal{V} \subseteq_{fin} [X_s \Rightarrow X_t]$ and $\{|\mathcal{U}\}\langle \mathcal{V}\rangle$, then \mathcal{V} is a complete set of upper bounds for U .

Proof. If $V \in V$, then $\bigcup \mathcal{U} \sqsubset V$ and so $U \sqsubset V$ for all U in U. If $W : [X_s \Rightarrow X_t]$ is an upper bound for U, then $\bigcup \mathcal{U} \subseteq f_W$ and so $\bigcup \mathcal{U} \sqsubseteq V \subseteq f_W$ for some V in V, so $V \sqsubseteq W$.

Our strategy now is as follows. We define a geometric formula $\Phi(\mathcal{U}_1, \mathcal{U}_2)$ contained in \lt , which is to represent a single iteration of Abramsky's algorithm (which is nondeterministic). Since < is a preorder, the re
exive transitive closure (which is still geometric) is also contained in \lt . CUB₀($\mathcal{U}_0, \mathcal{U}$) is then defined as $\Phi^*(\{\dagger \mathcal{U}_0\}, \mathcal{U})$ and Lemma $4.4.3$ gives us everything we need except for existence. (In effect, the algorithm has a loop invariant $\{U_0\} < U_1$ We then show that for every $U_0 \subseteq_{fin} X_s \times X_t$ there is some $\mu \subset_{\text{fin}} \vert A_s \Rightarrow A_t\vert$ such that $\Psi \vert \{U_0\},\mathcal{U}\}\vert$ and this corresponds to the termination proof of the algorithm (if executed judiciously enough).

Before Φ , we first define a geometric predicate $\Psi(U_0, \mathcal{U}; V, W_s, W_t, M_s, M_t)$ as -

- $-M_i$ is a CUB-closed finite subset of X_i and $W_i \subseteq_{fin} M_i$ $(i = s, t)$
- [|] ^V n U0 n Ms Mt
- $-W_s$ and W_t are complete sets of upper bounds for $p_s(V)$ and $p_t(V)$
- $-U = \{U_0 \cup R \mid R \text{ a finite, total relation from } W_s \text{ to } W_t\}$ (finite, by Lemma 2.1.10)

if we are just given by the UO will work and we can construct the controlly and we can certain a second where U such that U is U in U $U_0 \cup R$, and U in effect represents the different possible ways of extending U_0 to include a summary of V .

Lemma 4.4.4. Suppose $\Psi(U_0, U; V, W_s, W_t, M_s, M_t)$ and $U_0 \subseteq f$ with f an approximable mapping. Then $U_0 \sqsubseteq U \subseteq f$ for some U in \mathcal{U} .

Proof. $V \subseteq$ f_{fin} J , so for each x in W_s we have $x \not\mid y$ for every (x, y) in V and hence we can find y such that x f y and y is an upper bound for $p_t(V)$ and without loss of generality $y \in W_t$. Hence there is a finite total relation R from W_s to W_t such that $R \subseteq f$, which is what we wanted. \blacksquare

In defining Φ , we shall fix M_s and M_t – this is needed in order to provide finite bounds. $\Psi(u_1, u_2)$ ($u_1, u_2 \subseteq_{\text{fin}} \mathcal{F}(M_s \times M_t)$) shall then mean that there are U_0, u_1, v_2, u_3, w_s and W_t such that

$$
U_1 = \{U_0\} \cup \mathcal{U}'
$$

$$
\Psi(U_0, \mathcal{U}; V, W_s, W_t, M_s, M_t)
$$

$$
\mathcal{U}_2 = \mathcal{U} \cup \mathcal{U}'
$$

In other words, we have selected from U_1 an element U_0 and a subset V, found corresponding W_s , W_t and U for Ψ , and replaced U_0 in U_1 by the elements of U to get u_2 . It is plain that Ψ is contained in \lt , so Ψ is too. Note also that if $\Psi(\mathcal{U}_1,\mathcal{U}_2)$ then $\Psi(U_1 \cup V, U_2 \cup V)$, and so the same goes for Ψ . We can deduce that if Ψ (U_i, V_i) $(1 \leq i \leq n)$, then $\Phi^*(\bigcup_i \mathcal{U}_i, \bigcup_i \mathcal{V}_i)$.

Finally, we must prove termination. This is quite subtle, for the algorithm is nondeterministic and can easily go into an infinite loop by selecting unintelligent choices. Hence the proof must in effect also show how to find a terminating branch and how to know when to terminate.

Lemma 4.4.5. Let M_s and M_t be finite CUB-closed subsets of X_s and X_t , and suppose $U_0 \subseteq_{fin} M_s \times M_t$. Then there exists $VV \subseteq_{fin} \{X_s \Rightarrow X_t\}$ such that $\Psi(\{U_0\}, VV)$.

 $-$ - - - - $-$ - \cdots - - - \cdots \cdots B n F(Ms - Mt) as

$$
\forall U \subseteq_{\text{fin}} M_s \times M_t.
$$

$$
((U \cup A = M_s \times M_t \wedge B \subseteq \mathcal{F}(U) \wedge \forall V \subseteq_{\text{fin}} U.(V \in B \vee V \text{ has a summary in } U))
$$

$$
\rightarrow \exists W \subseteq_{\text{fin}} [X_s \Rightarrow X_t].\Phi^*(\{U\}, W))
$$

We shall prove that $\forall A, \mathcal{B}.P(A, \mathcal{B})$, using strong F-induction (Theorem 2.1.11) on A and simple F-induction (Theorem 2.1.3) on β . Effectively, the induction on β is an induction on the number of subsets of U not yet checked to have a summary, while that on a induction on the number of the numbers of Ms $_{\alpha}$, and $_{\beta}$ are $_{\beta}$, the second comments of elements" do not of course exist as genuine cardinalities (for which we would need decidable equality on the elements), but they are there as lengths of lists representing the finite sets and this is seen explicitly in Abramsky's account. We have chosen to work more abstractly, without using explicit list representations, but nonetheless you can see them in the proof of 2.1.11. For a given U0, the result will follow from P (Ms-Mt; F(U0)).

The outer induction is on A , so let us fix A with the induction hypothesis that

$$
\forall a \in A. \exists A' \subseteq_{\text{fin}} M_s \times M_t. (A = \{a\} \cup A' \land \forall \mathcal{B}. P(A', \mathcal{B}))
$$

We shall prove $\forall \mathcal{B}.P(A,\mathcal{B})$ by simple induction on $\mathcal{B}.$ First, $P(A,\emptyset)$ is obvious: if U satisfies the conditions to the left of the implication, then it is already fully summarizing, so we can take $W = \{U\}$. Next, we assume $P(A, \mathcal{B})$ and prove $P(A, \{V\} \cup \mathcal{B})$. Let U satisfy the premisses of the implication. Starting from the given $V \subset_{fin} U$, we can find $\mathcal{U},\,W_s$ and W_t so that $\Psi(U,\mathcal{U};V,W_s,W_t,M_s,M_t)$. If R is a finite total relation from W_s $\tau \in W$, then reduces $\tau = \tau$, then τ , then τ is the RU and RU a that $R = R_U \cup R_A$. If $R_A = \emptyset$, then $R \subseteq U$ and so V has a summary in U. Hence U also satisfies the premisses in $P(A, \mathcal{B})$, so by induction we can find W as required. If $R_A \neq \emptyset$ (remember that emptiness is decidable for finite sets) then take some $a \in R_A$. By the induction hypothesis, we can find $A \subseteq_{fin} M_s \times M_t$ such that $A = \{a\} \cup A$ and VD. P (A), D). Now $U \cup R$ satisfies the premisses for $P(A, \mathcal{F}(U \cup R))$ and so we can find suitable W . We have now shown that

$$
\forall U' \in \mathcal{U} \exists \mathcal{W} \subseteq_{\text{fin}} [X_s \Rightarrow X_t]. \Phi^*(\{U'\}, \mathcal{W})
$$

Now by taking the union of finitely many such ν s we can find $\nu\nu$ such that $\Psi^-(\mathcal{U},\nu\nu)$; and since $\Phi({U}, U)$ the result follows. \blacksquare

The algorithmic content of this is as follows. A state is a finite set σ of triples (U_1, A, B) such that \mathcal{S}_1 is the mass of \mathcal{S}_2 , \mathcal{S}_3 and \mathcal{S}_4 and \mathcal{S}_5 . The summary intermediate \mathcal{S}_4 U_1 : hence the induction variables A and B appear explicitly in the computation. The reason for this is that in order to know when to terminate, we must recognize when our U_1 s are fully summarizing and β contains the subsets V for which we must still check for the existence of summaries or create summaries using Ψ . Using Ψ changes U_1 and so the checking must start all over again, but occurences of this are limited by A which contains the elements not already known to be in U_1 . We also have the loop invariant $\{U_0\} < \{U_1 \mid (U_1, A, B) \in \sigma\}$. A step in the algorithm is then -

- select (U_1, A, B) from σ with $B \neq \emptyset$ (if there are none, we can stop)
- \longrightarrow select $V \in \mathcal{B}$, leaving $\mathcal{B} = \{V\} \cup \mathcal{B}'$
- $-$ find U, W_s and W_t so that $\Psi(U_1, U; V, W_s, W_t, M_s, M_t)$
- for each finite total relation R from W_s to W_t , decomposed as $R_U \cup R_A$, find a corresponding new state element (U_1, A, D) if $R_A = \emptyset$, or $(U_1 \cup R, A, \mathcal{F}(U_1 \cup R))$ if $a \in R_A$, where A is A with a removed $=$ or at least, one occurrence of a is removed from the representation of A.
- The new state is the old state σ with (U_1, A, \mathcal{B}) replaced by all the new state elements just found.

We have now proved that if X_s and X_t are strongly algebraic information systems, then so is $[X_s \Rightarrow X_t]$ – so we have defined a geometric morphism EXP : $[IS]^2 \rightarrow [IS]$.

Proposition 4.4.6. The points of $[X_s \Rightarrow X_t]$ are equivalent to approximable mappings from X_s to X_t .

Proof. If I is an ideal of $[X_s \Rightarrow X_t]$ then we can define an approximable mapping f as the union of the f_{U} s for U in I. Conversely, if f is an approximable mapping, then let I be

the set $\{U \in [X_s \Rightarrow X_t] \mid U \subseteq f\}$. The only point of difficulty so far is the ideal property of *I*. Suppose $U_i \in [X_s \Rightarrow X_t]$, $U_i \subseteq f$ $(1 \leq i \leq n)$. We can find $\mathcal{U} \subseteq_{\text{fin}} [X_s \Rightarrow X_t]$ such that $\Phi^*(\{\bigcup_i U_i\}, \mathcal{U})$, and then because $\{\bigcup_i U_i\} < \mathcal{U}$ we have by Lemma 4.4.3 that the U_i s have an upper bound contained in f.

Now suppose we start with I , construct J as above, and then construct I from J . If $U \in I$ then $U \subseteq JU \subseteq J$, so $U \in I$. On the other hand, if $U \in I$ then for each $u \in U$ we can find U in I such that $u \in J_{U'}$, and by taking an upper bound U in I we have each $u \in J_{U^{\prime\prime}}$ and so $U \sqsubseteq U$, $U \in I$.

 ${\bf r}$ many, suppose f is an approximable mapping, let I be defined as above, and then f from 1. If x f y then x f_{U} y for some $U \subseteq f$ and so x f y . If x f y then we can find $\mathcal U$ such that $\Psi_-(\{ \{x,y\}\}\})$, $\mathcal{U}_+(\mathcal{U}_\mathcal{U})$, and $\{ \{x,y\}\in U\subseteq J$ for some $U\in \mathcal{U}_\mathcal{U}$, so $(x,y)\in JU$ and $x \, y \, y$.

We have now proved $-$

Theorem 4.4.7. If X_s and X_t are strongly algebraic information sytems then so is $[X_s \Rightarrow X_t]$, and its points are equivalent to approximable mappings from X_s to X_t .

It follows that, as we wanted, $[Am]$ is a strongly algebraic domain over $[D]$.

4.5. Power domains

Robinson (1986) showed that the well-known Hoare, Smyth and Plotkin (or lower, upper and convex) power domains can be constructed localically, and in fact they are instances of more general powerlocale constructions P_L (lower), P_U (upper) and V (Vietoris). V originated in Johnstone (1982a), while the simpler P_L and P_U are folklore. A constructive account of all three can be found in Vickers (1997).

Definition 4.5.1. Let X be an information system. The lower, upper and convex power domains, $P_L X$, $P_U X$ and $P_C X$, are defined respectively as follows:

- \longrightarrow They all have the same tokens, namely $\mathcal{F}X$.
- $-$ They have preorders defined as $-$

$$
S \sqsubseteq_L T \sqsubseteq_{\text{def}} \forall s \in S. \exists t \in T. s \sqsubseteq t
$$

$$
S \sqsubseteq_U T \sqsubseteq_{\text{def}} \forall t \in T. \exists s \in S. s \sqsubseteq t
$$

$$
S \sqsubseteq_C T \sqsubseteq_{\text{def}} S \sqsubseteq_L T \land S \sqsubseteq_U T \text{ (the } \textit{Egli-Milner ordering)}
$$

Note that because these are preorders, Proposition 4.0.8 is needed, though we shan't dwell on the details.

Note also that we do not follow the common convention of excluding the empty set (though there is no constructive problem in doing so if that is what is required). Consequently, each domain includes an "empty" point $-$ in P_L it is bottom, in P_U it is top and in V it is isolated.

The ideal completions of these are homeomorphic to the corresponding powerlocales, and a general proof (covering non-local domains as well as continuous domains) is in Vickers (1993). In what remains, the hard work amounts to a proof that if a domain is spectral algebraic, then so are its power domains.

 CUB_L and CUB_U come out from the fact that \sqsubseteq_L and \sqsubseteq_U both make $\mathcal{F}X$ into a join (pre-)semilattice: the join of S and T in $P_L X$ is $S \cup T$, while in $P_U X$ it is got by taking a union of sets U_{st} such that $\text{CUB}(\{s, t\}, U_{st})$ $(s \in S, t \in T)$. The nullary join (bottom element) in $P_L X$ is \emptyset , and in $P_U X$ it is any S for which CUB(\emptyset , S).

Let us now concentrate on the convex powerdomain. Just as for the function space, the essential working is already in Abramsky (1991), so this time we shall do no more than sketch the information system account. If $\mathcal{U}: \mathcal{FF}X$, then we need to ask when $T: \mathcal{F}X$ is an upper bound for U. For every $U \in \mathcal{U}$ we have $U \sqsubseteq_L T$ and $U \sqsubseteq_U T$. From the former we get that $V \sqsubseteq_L T$ where $V = \bigcup \mathcal{U}$, while from the latter we get that for each t in T there is some choice function ϕ on U such that t is an upper bound for $\{\phi(U) \mid U \in \mathcal{U}\}\)$. Hence $W \sqsubseteq_U T$ where $W = \bigcup_{\phi} W_{\phi}$ for some W_{ϕ} with $\mathrm{CUB}(\{\phi(U) \mid U \in \mathcal{U}\}, W_{\phi})$. Actually, to give a properly constructive account, we need to consider not choice functions but choice relations on U, finite total relations R from U to $\bigcup U$ such that if U R s then $s \in U$. One can show by techniques similar to those of Lemma $2.1.10$ that the set of finite choice relations on U is finite.

We have thus replaced U by a pair (V, W) such that the upper bounds (under \sqsubseteq_C) of U are those T such that $V \sqsubseteq_L T$ and $W \sqsubseteq_U T$. If we had $V = W$, then we'd have $V\sqsubseteq_C T$ and so V would be a least upper bound of \mathcal{U} ; and if we only had $W\sqsubseteq_C V$ then still $V \cup W$ would be a least upper bound for U. In general we don't have a least upper bound, but our aim is to work towards a set of pairs (V, W) such that the upper bounds of U are those T for which $V \sqsubseteq_L T$ and $W \sqsubseteq_U T$ for some (V, W) in the set. For each such pair, if we don't yet have $W \sqsubseteq_C V$ (but of course this negative statement must be treated rather circumspectly just as for the function space) then we can replace it by a set of better pairs.

The two cases, forming the basis for the (simple \mathcal{F} -) induction, are as follows.

- Consider $(V \cup \{s\}, W)$. For each $w \in W$ we can find U_w such that $\text{CUB}(\{s, w\}, U_w);$ let $U = \bigcup_{w} U_w$. Then we can replace $(V \cup \{s\}, W)$ by $\{(V \cup \{u\}, W) \mid u \in U\}$. For if $V \cup \{s\} \sqsubseteq_L T$ and $W \sqsubseteq_U T$ then $s \sqsubseteq$ some $t \in T$, and $t \sqsupseteq$ some $w \in W$, so $t \sqsupseteq$ some $u \in U_w$ and $V \cup \{u\} \sqsubseteq_L T$. Conversely, if $V \cup \{u\} \sqsubseteq_L T$ for some $u \in U_w$ then $s \subseteq u$ so $V \cup \{s\} \subseteq_L T$. Now if $u \in U_w$ then $u \supseteq w$, and by iterating the process we can ensure $W \sqsubset_U V$ in each pair.
- We can replace $(V, W \cup \{s\})$ by $\{(V, W), (V \cup \{s\}, W \cup \{s\})\}$. For if $W \cup \{s\} \sqsubseteq_U T$ then either $W \sqsubseteq_U T$ or $s \sqsubseteq$ some $t \in T$, in which case $V \cup \{s\} \sqsubseteq_L T$. Both these new pairs help to make $W \sqsubseteq_L V$. We might no longer have $W \sqsubseteq_U V$, but we can restore this by the first case.

To complete the proof of strong algebraicity, if \mathcal{U} : $\mathcal{FF}X$ let M be CUB-closed containing \Box Then $\mathcal{F}M$ is CUB-closed containing U.

4.6. Decidable information systems

The information systems discussed so far have been undecidable in that the order \Box did not have a complement. It is interesting that [decIS], the topos classifying decidable information systems, also gives a topical CCC. It is genuinely different from $[IS] -$ it does

not happen that by some quirk the general \sqsubseteq has a complement. This is easily seen by considering the information system homomorphisms: if \sqsubseteq did in general have a complement, then it would have to be preserved by homomorphisms, so the homomorphisms would have to correspond to embedding-projection pairs rather than to the more general adjunctions that are clearly possible in the light of Proposition 4.0.6.

In [decIS], the proof of Cartesian closedness can be understood as a justied use of classical logic: the decidability of \Box enables us geometrically to bring \neg and \neg into order-theoretic statements, while \forall is possible because the SFP axioms give finite sets with which \forall can be bounded. Hence one can mimic classical proofs of the Cartesian closedness of the category of posets.

Abramsky (1991) describes his constructions inductively without $\not\sqsubseteq$, and is in effect giving what is needed to show Cartesian closedness for [IS]. However (his theorem 4.2.7), he also proves that \Box is decidable. This paradox arises because he is considering only the types that arise in his inductive system. Part of his proof shows how $\not\sqsubset$ can be defined inductively, and in fact this provides the ingredients for another proof that [decIS] also gives a topical CCC.

Note that if a strongly algebraic information system X has decidable order, then CUB is also decidable: for its negation \neg CUB(S, T) is the geometric formula

$$
\exists s \in S, t \in T. s \not\sqsubseteq t \lor \exists u. (\forall s \in S. s \sqsubseteq u \land \forall t \in T. t \not\sqsubseteq u)
$$

5. Solving domain equations

Recall that Theorem 2.3.8 showed the existence of fixpoints (more precisely, initial structures) for endomaps of local toposes (i.e. toposes with initial points). Restricting to the case of locales we get a more elementary case, that locales with bottom points have xpoints for endomaps.

Fixpoints within domains are thus covered by the localic case of Theorem 2.3.8. We shall not dwell on this except to note that our domains are not necessarily local and so Corollary 2.3.9 is the appropriate form: if $f: D_{\perp} \to D$ then up; f has a least fixpoint Y f (find the least fixpoint of f ; up in D_{\perp} in the standard way, and then apply f to it). Y can be internalized by the usual sort of CCC manipulations (and following the techniques of Hyland and Pitts (1989)) as something of polymorphic type $(D_{\perp} \Rightarrow D) \Rightarrow D$ as follows. That type corresponds to a map from [IS] to itself (map X to $[[X_{\perp} \Rightarrow X] \Rightarrow X]$). Pulling back the generic domain along this gives a topos E that classifies an information system X equipped with a point of $[[X_{\perp} \Rightarrow X] \Rightarrow X]$. Y is then a map from [IS] to E over [IS].

For fixpoints *amongst* domains, solving domain equations, we need Theorem 2.3.8 in its topos generality. This raises coherence questions but is conceptually unproblematic and relies on the feature of geometric theories that their classes of models are closed under filtered colimits by quite concrete constructions.

A standard approach $-$ such as Abramsky's (1991) $-$ would solve a domain equation $D \cong F(D)$ by restricting to local domains, so let us briefly investigate those.

Proposition 5.0.1. An algebraic dcpo Idl X is local iff X has a least element.

Proof. \Rightarrow : If \perp is the least element, then $\{\perp\}$ is an ideal contained in every other.

 \Leftarrow : Let I be the bottom ideal. It is inhabited, so it has an element x. Now $I \sqsubseteq \downarrow y$ for every y in X, so $x \sqsubseteq y$ and x is a least element of X.

Amongst the strongly algebraic information systems, the ones whose ideal completion is local form a subtopos [locIS] (an open subtopos, in fact): they are characterized by the additional axiom $\vdash \exists s : X$. CUB $(\emptyset, \{s\})$, for CUB $(\emptyset, \{s\})$ holds iff s is a bottom element of X. Since we are working with posets, the bottom element is unique, and we write \perp for it as usual. (For general algebraic information systems, the local ones do not form a subtopos because the bottom has to be specified as extra structure.)

Proposition 5.0.2. [locIS] is local.

Proof. The initial local information system is the singleton $\{\perp\}$. For any other local information system X, the unique homomorphism maps \perp to \perp - uniqueness arises because a homomorphism must preserve the bottom-defining property $\text{CUB}(\emptyset, \{s\})$.

Therefore, let $F : [\text{locIS}] \to [\text{locIS}]$ be any endomap. By Theorem 2.3.8 [F-Str] is local; its initial point is the canonical solution to $D \cong F(D)$.

However, there is a small issue of constructivity here. Such local information systems are closed under all the constructions given except ${\bf -}$ obviously ${\bf -}$ coproducts. It is usual to substitute a different sum construction, either the coalesced sum (which identifies the bottoms) or the separated sum (which adjoins a new one). Abramsky uses the coalesced sum, because it is more general $-$ the other can be defined using it. However, in defining CUB for the coalesced sum it turns out that one needs to know when tokens are not bottom, for one needs to say that $CUB(S, \emptyset)$ if S contains non-bottom elements from both summands. This information is not available in a general strongly algebraic information system with bottom, for if it were then non-bottomness would have to be preserved by homomorphisms. (For a counterexample, consider $\{\perp, \top\}$ mapping to $\{*\}\$.) Abramsky solves the problem by introducing a predicate T (for Termination) which would correspond in our system to an extra predicate $T(s)$ on X with axioms to make it the complement of $\text{CUB}(\emptyset, \{s\})$. He then shows how - in our terms - all the constructions yield information systems with such a predicate. The classier for these local information systems with termination predicate is again local, so the same techniques can be applied.

In solving $D \cong F(D)$, it is a well-known fact that F ought really to have some properties of continuity. In our topical setting it hardly makes any sense for F to be other than a geometric morphism, and then the continuity is automatic $-F$ will preserve filtered colimits, and this is the categorical analogue of Scott continuity. What's more, F does not in this setting have to be functorial with respect to continuous maps between domains, and there is no problem in using examples such as $X \rightarrow [X \Rightarrow X]$, which is a perfectly good geometric morphism. (It is the composite Δ ; EXP.) It is, of course, functorial with respect to homomorphisms between information systems, and, following Proposition 4.0.6, this is an interesting route to the usual trick of using endofunctors on the category of domains and embedding-projection pairs. (We have a slight variant here $-$ the homomorphisms are adjoint pairs rather than embedding-projection pairs. The trick still works, as was pointed out by Taylor (1986). As mentioned in Section 4.6, the difference corresponds to whether the order \sqsubseteq is decidable or not.) Let us emphasize this. The domain construction F does not need to be part of a functor on the topical

category. The very act of defining the transformation (geometrically) on objects gives us all the functoriality and continuity that we need.

Let us also describe an approach that works in the context of our non-local domains. We show how to solve a simple form of domain equation, namely $D \cong (F(D))_{\perp}$ where F is a construction on our domains without bottom. This is not quite as general as Abramsky's domain construction; it cannot, for instance, be used to construct the lifted natural numbers, because the natural numbers do not constitute a strongly algebraic domain (see note 6 after Definition $4.0.3$). However, the form does cover many important domain equations, and can often be pleasantly simple. For instance, the domain of lists over a nume decidable set A can be described by the domain equation $D = (1 \pm A \wedge D) \perp$ where $+$ and the categorical coproduct: the product: there is no need to use coalesced sum or smash product.

Theorem 5.0.3. Let $F : [IS] \rightarrow [IS]$ be a geometric morphism. Then F; LIFT has an initial structure.

Proof. LIFT : $[IS] \rightarrow [IS]$ factors via [locIS], which is local, so we can use Proposition 2.3.7 and Theorem 2.3.8.

The techniques just presented are in essence not so far from those already familiar from the information system approach to domains (Larsen and Winskel 1984) and followed in Abramsky (1991). However, one obvious difference is that we take a filtered colimit in a category of information systems rather than a directed join in a cpo (such as Abramsky's DPL1, a cpo of prelocales). Though this looks more complicated, it has a number of advantages. First, the underlying Theorem 2.3.8 is very general indeed in the way it exploits the topological nature of toposes, and it could equally well be applied in contexts such as that of quasimetric spaces in Vickers (1997a). Second, it uses directly the category structure (homomorphisms between models) that is naturally present. To get a cpo Abramsky must restrict to the monomorphisms, and though it works in the present case it still involves a little extra effort to show that the domain constructions are functorial with respect to them. Third, to get a real cpo requires great syntactic discipline for the order to be actual subset inclusion between the domain prelocales. This would be difficult to sustain in an elementary topos, in general lacking an intrinsic element-of relation.

6. Conclusions

By respecting the constructive constraints of geometric logic, we have followed Stone's dictum and topologized a signicant portion of domain theory. The possibility of topologizing within domains (i.e. of treating the domains themselves as topological spaces or ${ - \text{ as here - locales}}$ is already known, though by no means the standard view. However, we have also topologized *among* the domains, replacing ordinary categories of domains by topical categories, and this requires Grothendieck's generalized sense of topology.

The "within" and the "among" have always been recognized as having a lot in common, as seen for instance in the similarities between two characteristic constructions of domain theory $-$ on the one hand that of least fixpoints of endomaps, and on the other that of

solutions of domain equations. The wholesale topologization now presents these as two applications of our single very general Theorem 2.3.8 (the algebraic completeness of local toposes), in which generalized topological structure is seen as including filtered colimits. At the same time there is a pleasing and unexpected rational reconstruction of the way embedding-projection pairs are used in domain theory ${\rm -}$ they, or, more generally, adjunctions, arise in a completely natural way as homomorphisms of information systems.

The study therefore gives support to the topological view of domain theory by showing that it can be followed through in a cohesive way that brings out underlying connections and insights. Domain theory is not just about cpos! Nonetheless, much work still remains to be done if established results of domain theory are to be put in a topical setting. As a simple but deep example, Pitts (1996) gives an elegant domain-theoretic account of induction and coinduction, yet right from the start his treatment of relations as subsets of domains is difficult to reconcile with domains as locales.

A more obvious fear on the part of the working domain theorist is that the topological view (let alone the localic one) is more complicated: that it must already be much harder to understand a domain as a local locale than as a cpo and that the grander step of replacing ordinary categories of domains by topical categories can only be for enthusiasts. The paper has therefore also served as a case study in the geometric style of mathematics, the "topology-free spaces" of Section 1.1, showing that the topos-theoretic machinery does not need to obtrude. We have shown how some non-trivial mathematics can be done quite naturally in this framework, and that it automatically enforces constructivist constraints of the kind that Abramsky required for his formal system. Moreover, we see the constructive mathematics going beyond the syntactic systems to the semantic domains and the metatheory (which in Abramsky (1991) still contained classical features).

6.1. Arithmetic universes: some speculations

Though the "topology-free spaces" are designed to make topos-theoretic work look friendly, the expositional style embodies a very radical mathematical tendency for within it the general notion of collection can no longer be adequately expressed in sets $-$ sets are seen as particularly "discrete" kinds of collections. The full generality is expressed in locales and toposes as spaces, collections of points. This is not unprecedented, for it develops the distinction between sets and classes. We know that the collections of sets, groups, categories, and so on are "too large" to be sets and instead must be considered classes, and they are toposes too in the sense that there are toposes classifying them. Indeed, the idea of topos as described by a logical theory is a natural development of the idea of class as described by a formula of set theory. However, the distinction between sets and non-sets is now not just one of "size". Ordinarily one thinks of locales as being "small" in that both a collection of points and the frame of opens can be constructed internally as ob jects in the base elementary topos of sets, but in the geometric mathematics locales can no longer be internalized in this way, for both the set of points (unless the locale is discrete) and the frame of opens are non-geometric constructions. Hence not only do the large structures fall beyond the reach of sets, but so also do the non-discrete topological structures.

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What we see, then, is a mathematics in which sets are rather limited $-$ by the geometric constraints - in what we can do with them, and their place often has to be taken by locales and toposes. For instance, if X and Y are sets then their exponential must be replaced by the localic exponential $Y = \text{its points}$ are still the functions from X to Y , but it is not discrete, having the point-open topology. The subob ject classier , whose elements are the subsets of 1, must be replaced by the Sierpinski locale \$, whose points are the same but which has a non-discrete specialization order; and power sets $PA = \Omega^{-1}$ must be replaced by the lower powerlocale $\Gamma_L \Lambda = \emptyset$ (vickers 1997). But why should we put up with this? What is wrong with the non-geometric constructions? In view of the beauty of the theory of elementary toposes, it seems perverse to reject Cartesian closedness of Set (notwithstanding the result of Section 3.1.1, purporting to show that the topos of sets is not Cartesian closed), powersets and subobject classifiers, and insist on replacing them with locale-theoretic substitutes.

Perhaps a clue can be found in the nature of equality. Joyal and Tierney (1984) characterize sets (in the sense of discrete locales) as those locales X for which the finite diagonals $\Lambda \to \Lambda^+$ are all open maps, so in particular equality is an open in Λ^+ . If we take at all seriously the idea that open means "finitely observable", we should then expect equality to be a finitely observable relation. Informally, we find that this property is in fact preserved by geometric constructions, but something goes wrong with exponentials equality between functions cannot be directly evaluated, as any functional programming interpreter will quickly point out. This kind of problem with equality may serve as an early warning that the collection of functions is not as "set-like" as we might have hoped.

There remains a fundamental problem with this idea of treating toposes (Grothendieck toposes) as the prime notion of collection and treating sets as a special case. The "topology-free space" definition of topos in Section 1.1 depended on geometric theories, the logic is infinitary, and the standard account says that the whole idea of geometric theory is parametrized by an underlying account of the objects used to index the infinities. This is given by an elementary topos as base: fix your base topos and you get a theory of Grothendieck toposes (bounded geometric morphisms) over it. To make this work, the elementary topos structure of the base certainly seems necessary.

However, it seems that in the work of this paper the infinities are restricted to those that can be accessed effectively through free algebra constructions. This emboldens us to hope that the full geometric logic is unnecessary, that it suffices to have coherent logic with assorted free algebras, and that the categories corresponding to (what we called) geometric universes could be replaced by Joyal's arithmetic universes (unpublished notes). Indeed, our choice of the phrase "geometric universe" was guided by this hope. It is still not immediate that the mathematics here would go through in arithmetic universes; on a number of occasions we use intuitionistic reasoning that would certainly not be interpretable. Nonetheless, the algorithmic flavour of the constructions gives us grounds to feel that it ought to work. The theory of arithmetic universe should be a finite essentially algebraic theory and therefore self-standing.

Of course, once into arithmetic universes, we should be be completely restricted in our set-theoretic constructions, for arithmetic universes are not in general Cartesian closed and do not have subob ject classiers or powersets. It would not be possible to present

frames or construct ideal completions "set-theoretically" as objects and we should be forced to use locales and toposes $-$ their concrete manifestation would be as "classifying" arithmetic universes presented (using essential algebraicity) by generators and relations derived from the effectively accessible geometric theories.

I should like to conclude with some speculation about constructive mathematics. Two distinct schools have come to bear on this work, the type theoretic typified by Martin-Löf, and the topos theoretic, and these two are not always in harmony. The type theory school is tightly dependent on syntax and Abramsky acknowledges its influence, which can be seen, for instance, in his domain prelocales. However, its interpretation of disjunction and existential quantification involves explicit choice that can make some of its reasoning invalid in elementary toposes. On the other hand, reasoning valid in elementary toposes can include impredicativity in a way that is objectionable to the type theorists $-$ they need algorithms and induction. It appears that the stronger constraints of geometric constructivity (preservation under inverse image functors) do something to eliminate this, and indeed the reasoning in this paper is very algorithmic in character. It is tempting to hope that if the ideas on arithmetic universes bear fruit they could reconcile the two schools, giving predicative (or inductive) reasoning valid in toposes at the same time as choice-free reasoning for type theory.

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